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**FIXPOINT** APPROACH TO THE THEORY OF COMPUTATION

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## FIXPOINT APPROACH TO THE THEORY OF COMPUTATION

by ..

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### Abstract

Following the **fixpoint** theory of Scott, we propose to define the semantics of computer programs in terms of the least fixpoints of recursive programs. This allows one not only to justify all existing verification techniques, but also to extend them to handle various properties of computer programs, including correctness, termination and equivalence, in a uniform manner.

Keywords and Phrases: Verification techniques, semantics of programming languages, least **fixpoints**, recursive programs, computational induction

CR categories: 5.23, 5.24

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## Introduction

Substantial progress has recently been made in understanding the mathematical semantics of programming languages as a result of Scott's **fixpoint** theory. Our main purpose in this paper is to introduce the reader to some applications of this theory as a practical tool for proving properties of programs.

The paper consists of two parts.

In Part 1 we first introduce the notion of a recursive program and its (unique) least **fixpoint**. We describe the computational induction method, a powerful tool for proving properties of the least **fixpoint** of a recursive program. We then illustrate how one could describe the semantics of an **Algol-like** program  $P$  by "translating" it into a recursive program  $P'$  such that the partial **function** computed by  $P$  is identical to the least **fixpoint** of  $P'$ . Works in this area include those of McCarthy [1963a, 1963b], Landin [1964], Strachey [1966], Morris [1968], Bekić [1969], Park [1969], deBakker and Scott [1969], Scott [1970], Scott and Strachey [1971], Manna, Ness and Vuillemin [1972], Milner [1972], Weyhrauch and Milner [1972].

In Part 2 of the paper we illustrate some of the advantages of the **fixpoint** approach to program semantics. First, we justify the **inductive** assertion methods of Floyd [1967] and Hoare [1969, 1971]. Other verification methods such as recursion induction (McCarthy [1963a], [1963b]), structural induction (Burstall [1969]), **fixpoint** induction (Park [1969], Cooper [1971]), and the predicate calculus approach (Manna [1969], Manna and Pnueli [1970]) can be justified in much the same way. Secondly, we emphasize that the **fixpoint** approach suggests a natural method for proving properties of programs: given a

program  $P$  , we can translate it into the corresponding recursive program  $P'$  , and then prove the desired properties for the least **fixpoint** of  $P'$  by computational induction. In contrast to other existing methods, this approach gives a uniform way of expressing and proving different properties, including correctness, termination and equivalence. This makes it very **convenient** for machine implementation (Milner [1972]).

Warning: The reader should be aware that some of the results presented in this paper hold only under certain restrictions which are ignored in this informal presentation.

## PART 1. THE FIXPOINT APPROACH TO PROGRAM SEMANTICS

### 1.1 Recursive Programs

A recursive program is a LISP-like definition of the form

$$F(\bar{x}) \Leftarrow \tau[F](\bar{x}) ,$$

where  $\tau[F](\bar{x})$  is a composition of base functions and the function variable  $F$  , applied to the individual variables  $\bar{x} = (x, y, z, \dots)$  . The following, for example, is a recursive program over the integers

$$P_0: F(x, y) \Leftarrow \underline{\text{if } x = y \text{ then } y+1 \text{ else } F(x, F(x-1, y+1))} .$$

We allow our base **functions** to be partial, i.e., they may be undefined for some arguments. This is quite natural, since they represent the result of *some* computation which may in general give results for some inputs and run indefinitely for others. We include as limiting cases the partial functions defined for all arguments, called total functions, as well as the partial **function** undefined for all arguments

Let us consider now the following partial functions:

$$f_1(x, y): x+1$$

$$f_2(x, y): \underline{\text{if } x \geq y \text{ then } x+1 \text{ else } y-1} , \text{ and}$$

$$f_3(x, y): \underline{\text{if } (x > y) \wedge (x-y \text{ even}) \text{ then } x+1 \text{ else } \underline{\text{undefined}}} .$$

These functions have an interesting common property: For each  $i$  ( $1 \leq i \leq 3$ ) , if we replace all occurrences of  $F$  in the program  $P_0$  by  $f_i$  , the **lefthand** side and the righthand side of the symbol  $\Leftarrow$  yield identical partial functions, i.e., <sup>\*</sup>

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<sup>\*</sup>  $\equiv$  is an extension of the regular  $=$  relation for handling undefined values.  $a \equiv b$  is true if both  $a$  and  $b$  are undefined, but it is false if only one of them is undefined.

$$f_i(x,y) \equiv \underline{\text{if } x = y \text{ then } y+1 \text{ else } f_i(x, f_i(x-1, y+1))}.$$

We say that the functions  $f_1$ ,  $f_2$  and  $f_3$  are fixpoints of the recursive program  $P_0$ .

Among the three functions,  $f_3$  has one important special property: for any  $(x,y)$  such that  $f_3(x,y)$  is defined, i.e.,  $(x \geq y) \wedge (x-y \text{ even})$ , both  $f_1(x,y)$  and  $f_2(x,y)$  are also defined and have the same value as  $f_3(x,y)$ . We say that  $f_3$  is "less defined than or equal to"  $f_1$  and  $f_2$ , and denote this by  $f_3 \sqsubseteq f_1$  and  $f_3 \sqsubseteq f_2$ . It can be shown that  $f_3$  has this property not only with respect to  $f_1$  and  $f_2$  but with respect to all fixpoints of the recursive program  $P_0$ . Moreover,  $f_3(x,y)$  is the only function having this property;  $f_3$  is therefore said to be the least (defined) fixpoint of  $P_0$ .

One of the most important results related to this topic is due to Kleene [1952], who showed that every recursive program  $P$  has a unique least fixpoint (denoted by  $f_P$ ).

In discussing our recursive programs, the key problem is:

What is the partial function  $f$  defined by a recursive program  $P$  ?

There are two viewpoints.

- (a) Fixpoint approach: Let it be the unique least fixpoint  $f_P$ .
- (b) Computational approach: Let it be the computed function  $C_P$  for some given computation rule  $C$  (such as "call by name" or "call by value").

We now come to an interesting point: all the theory for proving properties of recursive programs is based on the assumption that the

function defined by a recursive program is exactly the least fixpoint  $f_P$ . That is, the fixpoint approach is adopted. Unfortunately, many programming languages use implementations of recursion (such as "call by value" !) which do not necessarily lead to the least fixpoint (Morris [1968]).\*/

Let us consider, for example, the following recursive program over the integers

$$P_1 : F(x,y) \leq \text{if } x = 0 \text{ then } 1 \text{ else } F(x-1, F(x,y))$$

The least fixpoint  $f_{P_1}$  can be shown to be

$$f_{P_1}(x,y) : \text{if } x \geq 0 \text{ then } 1 \text{ else } \underline{\text{undefined}} .$$

However, the computed function  $C_{P_1}$ , where C is "call by value", turns out to be

$$C_{P_1}(x,y) : \underline{\text{if}} \ x = 0 \ \underline{\text{then}} \ 1 \ \text{else} \ \underline{\text{undefined}} .$$

Thus,  $C_{P_1}$  is properly less defined than  $f_{P_1}$  -- e.g.,  $C_{P_1}(1,0)$  is undefined while  $f_{P_1}(1,0) = 1$ .

There are two alternative ways to view this problem: (a) Existing computer languages should be modified, and language designers and implementors should seek computation rules which always lead to the least fixpoint. "Call by name" is one such computation rule, but unfortunately it often leads to very inefficient computations. An efficient computation rule which always leads to the least fixpoint can be obtained by modifying

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\*/ It can be shown in general that for every recursive program P and any computation rule C,  $C_P$  must be less defined than or equal to  $f_P$ , i.e.,  $C_P \sqsubseteq f_P$  (Cadiou [1972]).

"call by value" so that the evaluation of the arguments of a procedure is delayed as long as possible (Vuillemin [1972]). (b) Theoreticians are wasting their time by developing **fixpoint** methods for proving properties of programs which do not compute fixpoints. They should instead concentrate their efforts on developing direct methods for proving properties of programs as they are actually executed.

We shall indicate in Part 2 of this paper how the apparent conflict between these views can be resolved by a suitable choice of the semantic definition of the programming language.

## 1.2 The Computational Induction Method

The main practical reason for suggesting the **fixpoint** approach is the existence of a very powerful tool, the **computational** induction method, for proving properties of recursive programs. The idea of the method is essentially to prove properties of the least **fixpoint**  $f_P$  of a given recursive program  $P$  by induction on the level of recursion.

Let us consider, for example, the recursive program

$$P_2 : F(x) \leq \text{if } x = 0 \text{ then } 1 \text{ else } x \cdot F(x-1) ,$$

over the natural numbers. The least **fixpoint**  $f_{P_2}(x)$  of this recursive program is the factorial function  $x!$  .

Let us denote by  $f^i(x)$  the partial function indicating the "information" we have **after** the  $i$ -th level of recursion. That is,



$f^0(x)$  is undefined (for all  $x$ );

$f^1(x)$  is if  $x = 0$  then 1 else  $x \cdot f^0(x-1)$  ,  
i.e., if  $x = 0$  then 1 else undefined ;

$f^2(x)$  is if  $x = 0$  then 1 else  $x \cdot f^1(x-1)$  ,  
i.e., if  $x = 0$  then 1 else  $x \cdot (\text{if } x-1 = 0 \text{ then } 1 \text{ else undefined})$  ,  
or in short, if  $x = 0 \vee x = 1$  then 1 else undefined ;

etc.

In general, for every  $i$  ,  $i \geq 1$  ,

$f^i(x)$  is if  $x = 0$  x · f <sup>$i-1$</sup>  else  $f^{i-1}(x-1)$  ,

which is

if  $x < i$  then x! else undefined .

This sequence of functions has a limit which is exactly the least fixpoint of the recursive program; that is,

$$\lim_{i \rightarrow \infty} \{f^i(x)\} \equiv x! .$$

This will in fact be the case for any recursive program  $P$  : if  $P$  is a recursive program of the form  $F(\bar{x}) \leftarrow \tau[F](\bar{x})$  , and  $f^i(\bar{x})$  is defined by

$f^0(\bar{x})$  is  $\Omega$  (undefined for all  $\bar{x}$ ), and

$f^i(\bar{x})$  is  $\tau[f^{i-1}](\bar{x})$  for  $i \geq 1$  ,\*

then

$$\lim_{i \rightarrow \infty} \{f^i(\bar{x})\} \equiv f_P(\bar{x}) .$$

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\*/  
 $\tau[f^{i-1}]$  is the result of replacing all occurrences of  $F$  in  $\tau[F]$  by  $f^{i-1}$  .

This suggests an induction rule for proving properties of  $f_p$  : To show that some property  $\varphi$  holds for  $f_p$ , i.e.,  $\varphi(f_p)$ , we show that  $\varphi(f^i)$  holds for all  $i \geq 0$ , and that  $\varphi$  remains true in the limit; therefore we may conclude that  $\varphi(\lim_{i \rightarrow \infty} \{f^i\})$ , i.e.,  $\varphi(f_p)$ , holds.

Note that it is not true in general that  $\varphi$  remains true in the limit. For example, for the recursive program  $P_2$  introduced above,  $f^i(x)$  is the non-total function if  $x < i$  then  $x!$  else undefined, while  $\lim_{i \rightarrow \infty} \{f^i\}$ , i.e.,  $f_{P_2}$ , is the total function  $x!$ . Thus for  $\varphi(f)$  being "f is not total", we have that  $\varphi(f^i)$  holds for all  $i \geq 0$ , while  $\varphi(\lim_{i \rightarrow \infty} \{f^i\})$  does not hold. However, the limit property holds of a rather large class of  $\varphi$  (called "admissible predicates" -- see Manna, Ness and Vuillemin [1972]); in particular, all the predicates that we shall use later have this property.

There are two well-known ways to prove that  $\varphi(f^i)$  holds for all  $i \geq 0$ , the rules for simple and complete induction on the level of recursion.

(a) Simple induction:

if  $\varphi(f^0)$  holds and  $\forall i[\varphi(f^i) \Rightarrow \varphi(f^{i+1})]$  holds,  


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then  $\varphi(f_p)$  holds .  


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(b) Complete induction:

if  $\forall i\{\{\forall j \text{ such that } j < i\} \varphi(f^j)\} \Rightarrow \varphi(f^i)\}$  holds ,<sup>\*/</sup>  


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then  $\varphi(f_p)$  holds .  


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<sup>\*/</sup> Note that this includes implicitly the need to prove  $\varphi(f^0)$ , since for  $i = 0$  there is no  $j$  such that  $j < i$ .

The simple induction rule is essentially the " $\mu$ -rule" suggested by deBakker and Scott [1969], while the complete induction rule is the "truncation induction rule" of Morris [1971]. Scott actually suggested the more elegant rule

$$\frac{\text{if } \varphi(\Omega) \text{ holds and } \forall f[\varphi(f) \Rightarrow \varphi(\tau[f])] \text{ holds,}}{\text{then } \varphi(f_p) \text{ holds,}}$$

which does not assume any knowledge of the integers in its formulation. These rules generalize easily to systems of mutually recursive definitions.

Example: Consider the recursive programs

$$P_3: F(x,y,z) \Leftarrow \text{if } x = 0 \text{ then } y \text{ else } F(x-1, y+z, z)$$

and

$$P_4: G(x,y) \Leftarrow \text{if } x = 0 \text{ then } y \text{ else } G(x-1, y+2x-1).$$

We would like to prove, using computational induction, that

$$f_{P_3}(x, 0, x) \equiv g_{P_4}(x, 0) \quad \text{for any natural number } x.$$

(Both functions compute the square of  $x$ .)

For this purpose, we shall prove a stronger result than the desired one by simple computational induction. Proving a stronger result often simplifies proofs by induction, since it allows the use of a stronger induction hypothesis. So, using

$$\varphi(f, g): \forall x \forall y [f(y, x(x-y), x) \equiv g(y, x^2 - y^2) + 1],$$

we try to show that

$$\varphi(f, g): \forall x \forall y [f(y, x(x-y), x) \equiv g(y, x^2 - y^2) + 1]$$

holds. The desired result then follows by choosing  $x = y$ . The induction proceeds in two steps:

(a)  $\varphi(f^0, g^0)$ , i.e.,  $\forall x \forall y [f^0(y, x(x-y), x) \equiv g^0(y, x^2 - y^2)]$ .

Trivial, since  $\forall x \forall y [\text{undefined} \equiv \text{undefined}]$ .

(b)  $\forall i [\varphi(f^i, g^i) \Rightarrow \varphi(f^{i+1}, g^{i+1})]$ .

We assume

$$\forall x \forall y [f^i(y, x(x-y), x) \equiv g^i(y, x^2 - y^2)]$$

and prove

$$\forall x \forall y [f^{i+1}(y, x(x-y), x) \equiv g^{i+1}(y, x^2 - y^2)]$$

$$\begin{aligned} f^{i+1}(y, x(x-y), x) &\equiv \text{if } y = 0 \text{ then } x(x-0) \text{ else } f^i(y-1, x(x-y)+x, x) \\ &\equiv \text{if } y = 0 \text{ then } x^2 \text{ else } f^i(y-1, x(x-(y-1)), x) \\ &\equiv \text{if } y = 0 \text{ then } x^2 \text{ else } g^i(y-1, x^2 - (y-1)^2) \\ &\hspace{15em} \text{by the induction hypothesis} \\ &\equiv \text{if } y = 0 \text{ then } x^2 - 0^2 \text{ else } g^i(y-1, (x^2 - y^2) + 2y - 1) \\ &\equiv g^{i+1}(y, x^2 - y^2) \end{aligned}$$

### 1.3 Semantics of Algol-like Programs

Our purpose in this section is to illustrate how one can describe the semantics of an Algol-like program  $P$  by translating it into a recursive program  $P'$  such that the partial function computed by  $P$  is identical to the least **fixpoint** of  $P'$ . The features of Algol we consider are very simple indeed, but there is no theoretical difficulty in extending them,

The translation is defined blockwise: to each block B (or elementary statement) we associate a partial function  $f_B$  describing the effect of the block (or statement) on the values of the variables. For example,

begin x := x+1; y := y+1 end ,

will be represented by the function

$$f(x,y) \equiv (x+1,y+1) .$$

Functions are then combined to represent the whole program using the rule:

$$f_{B_1;B_2}(\vec{x}) \equiv f_{B_2}(f_{B_1}(\vec{x})) .$$

This definition is unambiguous, since composition of partial functions is associative, i.e.,

$$f_{B_3}(f_{B_1;B_2}(\vec{x})) \equiv f_{B_1;B_2;B_3}(\vec{x}) \equiv f_{B_2;B_3}(f_{B_1}(\vec{x})) .$$

All that remains to be done is to describe the partial function associated with each elementary statement of the language. For simplicity, we shall first consider only a "flowchartable" subset of a language, with no goto statements or procedure calls. We shall also ignore the problem of declarations.

1) Assignment statements

if B is  $x_i := E(\vec{x})$  where E is an expression,

$$f_B(\vec{x}) \text{ is } (x_1, \dots, x_{i-1}, E(\vec{x}), x_{i+1}, \dots, x_n) .$$

2) Conditional statements

if B is if  $p(\vec{x})$  then  $B_1$  ,

$$f_B(\vec{x}) \text{ is if } p(\vec{x}) \text{ then } f_{B_1}(\vec{x}) \text{ else } \vec{x} ,$$

and

if B is if p(x) then B<sub>1</sub> else B<sub>2</sub>,

f<sub>B</sub>(x̄) is if p(x̄) then f<sub>B<sub>1</sub></sub>(x̄) else f<sub>B<sub>2</sub></sub>(x̄) .

3) Iterative statements

if B is while p(x̄) do B<sub>1</sub> ; .

f<sub>B</sub>(x̄) is the least fixpoint of the recursive program

F(x̄) <= if p(x̄) then F(f<sub>B<sub>1</sub></sub>(x̄)) else x̄ .

Example: Let us consider the following program for computing in x the greatest natural number smaller than or equal to  $\sqrt{a}$ , i.e.,  $x^2 \leq a < (x+1)^2$ , where a is any natural number. (The computation method is based on the fact that  $1+3+5+\dots+(2n-1) = n^2$  for every  $n > 0$ .)

```
P5 : begin integer x,y,z;  
      x := 0; y := z := 1;  
      while y < a do  
        begin x := x+1;  
            z := z+2;  
            y := y+z;  
        end;  
      end.
```

The partial function computed by P<sub>5</sub> is identical to the least fixpoint of P'<sub>5</sub>, where

P'<sub>5</sub> : F<sub>0</sub>(a) <= F(a,0,1,1)

F(a,x,y,z) <= if y ≤ a then F(a,x+1,y+z+2,z+2)  
 else (a,x,y,z)

4) goto statements

There has been much discussion (see, for example, Dijkstra [1968], Knuth and Floyd [1971], Ashcroft and Manna [1971]) about the usefulness of goto statements: they tend to make programs difficult to understand and debug, and one might prefer to use while or for statements instead. Without entering further into this controversy, we shall see that the semantics of goto statements is quite complex. In particular, it may lead to systems of mutually recursive definitions, and (not too surprisingly) it is indeed harder to prove properties of programs with goto statements. We consider two simple cases.

If we have a block of the form

begin . . . ; L: B<sub>1</sub> ; . . . ; B<sub>i-1</sub> ; goto L ; B<sub>i+1</sub> ; . . . ; B<sub>n</sub> end ,

then we define

$f_{\text{goto } L; B_{i+1}; \dots; B_n}(\bar{x})$  to be the least fixpoint of the recursive program

$$F_L(\bar{x}) \leq f_{B_1; \dots; B_n}(\bar{x}) .$$

If we have a block of the form

begin . . . ; goto L ; B<sub>1</sub> ; . . . ; B<sub>i-1</sub> ; L: B<sub>i</sub> ; B<sub>i+1</sub> ; . . . ; B<sub>n</sub> end ,

then we define

$f_{\text{goto } L; B_1; \dots; B_n}(\bar{x})$  to be the least fixpoint of the recursive program

$$F_L(\bar{x}) \leq f_{B_1; \dots; B_n}(\bar{x}) .$$

Note that we have revised our rule of composition, since

$f_{B; B'}(\bar{x}) \equiv f_{B'}(f_B(\bar{x}))$  is not valid when B is a goto statement.

Similarly, if we wish to allow goto's which jump out of

iterative statements or branches of conditional statements, then we must change their semantic definition accordingly.

Example: Let us consider another version of  $P_5$ , using only the operations successor and predecessor.

```

P6: begin integer x,y,z;
      x := 0; y:= z := 1;
      L: if y ≤ a then
          begin integer t;
              x := x+1;
              z := z+1;
              t := z+1;
              M: if t > 0 then
                  begin y := y+1;
                      t := t-1;
                  goto M;
              end;
              z := z+1; goto L;
          end;
      end.

```

The partial function computed by  $P_6$  is identical to the least fixpoint of  $P_6^i$  where

$$P_6^i : F_0(a) \leq F_L(a, 0, 1, 1)$$

$$F_L(a, x, y, z) \leq \underline{\text{if}} \ y \leq a \ \underline{\text{then}} \ F_M(a, x+1, y, z+1, z+2)$$

$$\qquad \qquad \qquad (\underline{\text{else}} \ x, \ y, \ z)$$

$$F_M(a, x, y, z, t) \leq \underline{\text{if}} \ t > 0 \ \underline{\text{then}} \ F_M(a, x, y+1, z, t-1)$$

$$\qquad \qquad \qquad \underline{\text{else}} \ F_L(a, x, y, z+1)$$



Let us now define the semantics of simple procedures without parameters. We shall not discuss problems such as "side effects", parameter passing or the procedure copy-rule for call by name.

5) procedures

(a) For the non-recursive procedure

procedure P;B

(where P is the procedure name and B is its body), we define

$f_{\text{call } P}(\bar{x})$  to be  $f_B(\bar{x})$ .

(b) For the recursive procedure

procedure P; B[P],

we define

$f_{\text{call } P}(x)$  to be the least **fixpoint** of the recursive program  $F(\bar{x}) \leq f_{B[P]}(\bar{x})$

where occurrences of call P will be replaced by F in the semantic definition of  $f_{B[P]}$ .

6) An answer to the problem of "call by value"

Our semantic definition of recursive procedures assumes that the implementation of recursion in the language always leads to the least fixpoint. If this is not the case, we must change our semantic definition: to every program P we associate a recursive program P' such that the least **fixpoint** of P' will always be identical to the partial function computed by P. Consider, for example, the program

```
integer procedure P(integer x,y);
P := if x = 0 then 1 else P(x-1,P(x,y));
```

If the implementation is "call by name", its semantics will be

$f_{\text{call}} P(x,y)$  is the least fixpoint of

$F(x,y) \leq \text{if } x = 0 \text{ then } 1 \text{ else } F(x-1, F(x,y))$  .

However, if the implementation is "call by value", its semantics will be

$f_{\text{call}} P(x,y)$  is the least fixpoint of

$F(x,y) \leq \text{if } (x = 0) \wedge \text{def}(y) \text{ then } 1 \text{ else } F(x-1, F(x,y))$  ,

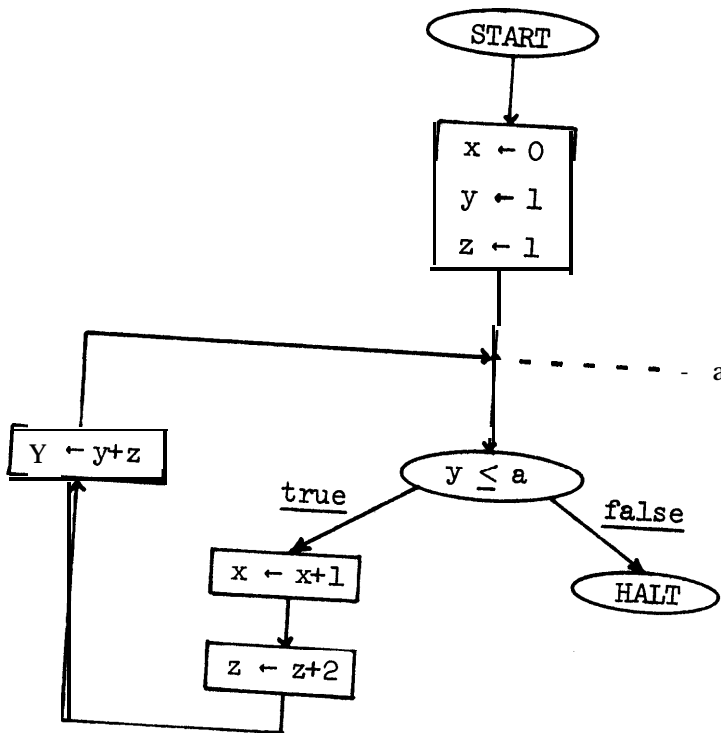
where the (computable) predicate  $\text{def}(y)$  is true whenever  $y$  is defined, and undefined otherwise.

PART 2. APPLICATION TO THE VERIFICATION PROBLEM

Our purpose in the second part of the paper is to illustrate some of the advantages of the fixpoint approach to program semantics.

2.1 Justification of the Inductive Assertions Method

The most widely used method for proving properties of "flowchart programs" is presently the inductive assertions method, suggested by Floyd [1967] and Naur [1966]. We shall illustrate the method on the simple program  $P_5$  above. To clarify our discussion we shall describe the program as a flowchart:



We wish to show that this flowchart program, whenever it terminates, computes the greatest natural number smaller than or equal to  $\sqrt{a}$ , i.e., that  $x^2 \leq a < (x+1)^2$ , for any natural number  $a$ .

To do this we associate a predicate  $Q(a, x, y, z)$ , called an inductive assertion, with the point labelled  $\alpha$  in the program, and show that  $Q$  must be true for the values of the variables  $(a, x, y, z)$  whenever execution of the program reaches point  $\alpha$ . Thus, we must show: (a) that if we start execution with  $a > 0$ , then the assertion holds when point  $\alpha$  is first reached, i.e., that  $Q(a, 0, 1, 1)$  holds; and (b) that the assertion remains true when one goes around the loop from  $\alpha$  to  $\alpha$ , i.e., that  $(y \leq a) \wedge Q(a, x, y, z)$  implies  $Q(a, x+1, y+z+2, z+2)$ . To prove the desired result we finally show (c) that  $x^2 \leq a < (x+1)^2$  follows from the assertion  $Q(a, x, y, z)$  when the program terminates, i.e., that  $(y > a) \wedge Q(a, x, y, z)$  implies  $x^2 \leq a < (x+1)^2$ .

To verify the program, we take

$$\underline{Q(a, x, y, z) \text{ to be } (x^2 \leq a) \wedge (y = (x+1)^2) \wedge (z = 2x+1) .}$$

One can then verify easily that conditions (a), (b) and (c) above, called the verification conditions, hold.

Hoare's inductive assertion method is actually a generalization of Floyd's method; Hoare [1969, 1971] realized that if we wish to apply the method of inductive assertions to prove properties of a large program, we shall undoubtedly have to break the program into smaller parts, prove what we need about the parts, and then combine everything together. We will clearly break the program into pieces in the most convenient way for the proof, and, since composition of statements is associative, the way in which we group the statements of the program is irrelevant. For example, if the given program is of the form

$$P: B_1; B_2; B_3; B_4 ,$$

we can associate the statements in several different ways, e.g.,

$$((B_1; B_2); B_2); B_3 ,$$

$$(B_1; (B_2; B_3)); B_4 ,$$

$$(B_1; B_2); (B_3; B_4) ,$$

or

$$B_1; (B_2; (B_3; B_4)) .$$

Although the programs do not look the same, all of them yield the same least fixpoint, and therefore they are equivalent. If we express other verification techniques using this notation, we find that Floyd and Naur consider only the first possibility, i.e., grouping statements to the left, while McCarthy [1963b] and Manna and Pnueli [1970] only consider the last possibility, i.e., grouping statements to the right.

Following Hoare, we express this idea by writing  $\{R\}B\{T\}$  <sup>\*/</sup> to mean that if  $R(\bar{x})$  holds before executing the piece of program B and if B terminates, then  $T(\bar{x})$  will hold after executing B .

We first apply verification rules to each statement of the program. Examples of such rules are:

(a) assignment statement rule:

$$\frac{R \supset S_{x_i}^{E(\bar{x})} \text{ implies } \{R\} x_i := E(\bar{x}) \{S\}}{\quad}$$

where  $S_{x_i}^{E(\bar{x})}$  stands for the result of replacing all occurrences of  $x_i$  in S by  $E(\bar{x})$  ;

---

<sup>\*/</sup> We prefer this notation to Hoare's  $R\{B\}T$  .

(b) conditional statement rule:

$$\frac{\{R_1\}B_1\{T\} \text{ and } \{R_2\}B_2\{T\} \text{ implies}}{\{\text{if } p(\bar{x}) \text{ then } R_1 \text{ else } R_2\} \text{ if } p(\bar{x}) \text{ then } B_1 \text{ else } B_2 \{T\}, \text{ */}}$$

(c) iterative statement rule:

$$\frac{\{R \wedge p(\bar{x})\} B \{R\} \text{ implies } \{R\} \text{ while } p(\bar{x}) \text{ do } B \{R \wedge \sim p(\bar{x})\}}{.}$$

We then compose pieces of the program until we get the entire program, using the following

(d) composition rule:

$$\frac{\{R\}B_1\{S\} \text{ and } \{S\}B_2\{T\} \text{ implies } \{R\}B_1;B_2\{T\}}{,}$$

(e) consequence rules:

$$\frac{R \supset S \text{ and } \{S\}B\{T\} \text{ implies } \{R\}B\{T\}}{\text{and}}$$

$$\frac{\{R\}B\{S\} \text{ and } S \supset T \text{ implies } \{R\}B\{T\}}{.}$$

Example. A proof of the correctness of the program  $p_5$ , given above, could be sketched as follows.

First, we establish, using the assignment statement rule, the following results:

Since  $a \geq 0 \supset R(a, 0, 1, 1)$ , where  $R(a, x, y, z)$  is  $(x^2 \leq a) \wedge (y = (x+1)^2) \wedge (z = 2x+1)$ , we get

$$(1) \quad (a > 0) \ x := 0; y := z := 1 \ \{R(a, x, y, z)\} .$$

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\*/ The reader should be aware of the difference between (if  $p$  then  $R_1$  else  $R_2$ ) in the mathematical language, which stands for  $(p \supset R_1) \wedge (\sim p \supset R_2)$ , and (if  $p$  then  $B_1$  else  $B_2$ ) in the programming language.

Since  $R(a, x, y, z) \wedge y \leq a \supset R(a, x+1, y+z+2, z+2)$  , we get

$$(2) \{R(a, x, y, z) \wedge y \leq a\} x := x+1; z := z+2; y := y+z \{R(a, x, y, z)\} .$$

By using the iterative statement-rule, we get from (2)

$$(3) \{R(a, x, y, z)\} \underline{\text{while } y \leq a \text{ do begin } x := x+1; \\ z := z+2; y := y+z \text{ end } \{R(a, x, y, z) \wedge y > a\} .$$

We now combine the results of (1) and (3) using the composition rule to obtain

$$(4) \{a \geq 0\} P_5 \{R(a, x, y, z) \wedge y > a\} .$$

Since  $[R(a, \bar{x}, y, z) \wedge y > a] \supset x^2 \leq a < (x+1)^2$  , we apply the consequence rule and finally get

$$(5) \{a \geq 0\} P_5 \{x^2 \leq a < (x+1)^2\} .$$

It is quite important that all of Hoare's verification rules can in fact be proved from the semantics we gave, just by using computational induction. We shall illustrate this point by justifying two of the most powerful verification rules: the rule for while statements, and the rule for call of recursive procedures. For this purpose, we need to relate the notation  $\{R\} B \{T\}$  to our  $f_B(\bar{x})$  , the partial function indicating the change of the values of the variables during the execution of B .

$\{R\} B \{T\}$  simply means that whenever  $R(\bar{x})$  is true,  $T(f_B(\bar{x}))$  is either true (if B terminates) or undefined. We can express this by the relation

$$R(\bar{x}) \Rightarrow T(f_B(\bar{x})) ,$$

adopting here the convention that  $a \Rightarrow b$  is true whenever  $a$  or  $b$  is undefined.

We are ready now to prove the following rules:

(a) rule for while statements

The verification rule for while statements indicates that if the execution of the body of the while statement leaves the assertion  $R$  invariant,  $R$  should hold upon termination of the while statement. More precisely,

$$\{R(\bar{x}) \wedge p(\bar{x})\} B \{R(\bar{x})\} \text{ implies } \{R(\bar{x})\} \text{ while } p(x) \text{ do } B \{R(\bar{x}) \wedge \sim p(\bar{x})\} .$$

We therefore have to prove the following theorem:

$$\begin{aligned} & \forall \bar{x} [R(\bar{x}) \wedge p(\bar{x}) \Rightarrow R(f_B(\bar{x}))] \\ & \text{implies} \\ & \forall \bar{x} [R(\bar{x}) \Rightarrow R(f_P(\bar{x})) \wedge \sim p(f_P(\bar{x}))] \text{ where} \\ & P : F(\bar{x}) \Leftarrow \underline{\text{if}} p(\bar{x}) \underline{\text{then}} F(f_B(\bar{x})) \underline{\text{else}} \bar{x} . \end{aligned}$$

The proof is by computational induction.

1.  $\forall \bar{x} [R(\bar{x}) \Rightarrow R(f^0(\bar{x})) \wedge \sim p(f^0(\bar{x}))]$  is clearly true according to our convention, since  $R(f^0(\bar{x}))$  and  $\sim p(f^0(\bar{x}))$  are undefined.
2. We assume  $\forall \bar{x} [R(\bar{x}) \Rightarrow R(f^i(\bar{x})) \wedge \sim p(f^i(\bar{x}))]$  and show  $\forall \bar{x} [R(\bar{x}) \Rightarrow R(f^{i+1}(\bar{x})) \wedge \sim p(f^{i+1}(\bar{x}))]$ . By definition of  $f^{i+1}$  we have

$$\begin{aligned} R(f^{i+1}(\bar{x})) & \Leftarrow \underline{\text{if}} p(\bar{x}) \underline{\text{then}} R(f^i(f_B(\bar{x}))) \underline{\text{else}} R(\bar{x}) , \text{ and} \\ p(f^{i+1}(\bar{x})) & \Leftarrow \underline{\text{if}} p(\bar{x}) \underline{\text{then}} p(f^i(f_B(\bar{x}))) \underline{\text{else}} p(\bar{x}) \end{aligned}$$



We distinguish between two cases:\*/

Case 2A:  $p(\bar{x})$  is false. Then,  $R(f^{i+1}(\bar{x})) \equiv R(\bar{x})$  and  $p(f^{i+1}(\bar{x})) \equiv p(\bar{x})$ , so that  $R(\bar{x}) \Rightarrow R(f^{i+1}(\bar{x})) \wedge \sim p(f^{i+1}(\bar{x}))$  is v&Lid.

Case 2B:  $p(\bar{x})$  is true. Then  $R(f^{i+1}(\bar{x})) \equiv R(f^i(f_B(\bar{x})))$  and  $p(f^{i+1}(\bar{x})) \equiv p(f^i(f_B(\bar{x})))$ . By the assumption  $R(\bar{x}) \wedge p(\bar{x}) \Rightarrow R(f_B(\bar{x}))$

holds, and since by the induction hypothesis

$R(f_B(\bar{x})) \Rightarrow R(f^i(f_B(\bar{x}))) \wedge \sim p(f^i(f_B(\bar{x})))$ , we get

$R(\bar{x}) \Rightarrow R(f^i(f_B(\bar{x}))) \wedge \sim p(f^i(f_B(\bar{x})))$ . Hence,

$R(\bar{x}) \Rightarrow R(f^{i+1}(\bar{x})) \wedge \sim p(f^{i+1}(\bar{x}))$  as desired.

(b) Rule for recursive calls

Let us consider a recursive procedure

procedure P; B[P],

where P is the name of the **procedure** and B[P] represents its body.

The verification rule for proving properties of P is quite similar to computational induction, although its formulation might look rather

paradoxical: in order to prove a property of the recursive procedure P,

one is permitted to assume that the desired property holds for the

body B[P] of the procedure! This can be stated as follows:

$\forall g [ \{R\} g \{T\} \text{ implies } \{R\} B[g] \{T\} ] \text{ implies } \{R\} \text{ call } P \{T\} .$

As Hoare [1971, p. 109] puts it, "this assumption of what we want to prove before embarking on the proof **explains** well the aura of magic which attends a programmer's first introduction to recursive programming".

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\*/ A more rigorous treatment would require checking also the case in which  $p(\bar{x})$  is undefined.

The rule however is easy to justify. We have to prove the following theorem:

$$\begin{aligned} & \forall g [\forall \bar{x} [R(\bar{x}) \Rightarrow T(g(\bar{x}))] \text{ implies } \forall \bar{x} [R(\bar{x}) \Rightarrow T(f_{B[g]}(\bar{x}))]] \\ & \text{implies} \\ & \forall \bar{x} [R(\bar{x}) \Rightarrow T(f(\bar{x}))] \text{ where} \\ & P: F(\bar{x}) \leq f_{B[F]}(\bar{x}) . \end{aligned}$$

The proof is again by computational induction.

1.  $\forall \bar{x} [R(\bar{x}) \Rightarrow T(f^0(\bar{x}))]$  is true, since  $T(f^0(\bar{x}))$  is undefined.
2. We assume  $\forall \bar{x} [R(\bar{x}) \Rightarrow T(f^i(\bar{x}))]$  and show  $\forall \bar{x} [R(\bar{x}) \Rightarrow T(f^{i+1}(\bar{x}))]$ .  
By the induction hypothesis,  $R(\bar{x}) \Rightarrow T(f^i(\bar{x}))$ , therefore, by the assumption of the theorem  $R(\bar{x}) \Rightarrow T(f_{B[f^i]}(\bar{x}))$ . Thus, from the definition of  $f^{i+1}$  we get  $R(\bar{x}) \Rightarrow T(f^{i+1}(\bar{x}))$ , as desired.

## 2.2 Translation to Recursive Programs

In the present state of the art of verifying programs, Hoare's method is presumably the most convenient for proving the correctness of programs. However, its main drawback is that it can handle only "partial correctness" (cf. [1], p. 11). In other words, we can only show that the final results of the programs, if they exist, satisfy some given input-output relation. The method, does not include any means for proving termination, and seems rather ill-fitted for proving equivalence between programs.

This is another case where our semantic definition of the programming language pays off: properties like termination and equivalence can be

handled in exactly the same way as partial correctness. The idea is quite simple: To prove some property of a given program  $P$ , translate it to the corresponding recursive program  $P'$ , and then prove the desired property for  $f_{P'}$ , by computational induction. In this method we actually still benefit from all the advantages of Hoare's approach since we may associate the blocks of the program arbitrarily at our convenience.

To show, for example, that the partial function defined by the given program  $P$  is monotonic increasing, we prove

$$\forall x, y [ (x < y) \Rightarrow (f_{P'}(x) \leq f_{P'}(y)) ] .$$

Note that it is rather hard to express such a property as an input-output relation.

(A) Termination

To show that  $f_P$  is total, or in general that  $g \sqsubseteq f_P$  for some function  $g$  which is total on the desired domain, we cannot simply use computational induction choosing  $\varphi(F)$  to be  $g \sqsubseteq F$ , as then  $\varphi(f^0)$  will always be false. However, we can overcome this difficulty by considering the domain over which our data range as defined by a recursive program.

For example, the natural numbers can be characterize<sup>\*/</sup> by the least fixpoint num(x) of the recursive program

$$N(x) \Leftarrow \text{if } x = 0 \text{ then true else } N(x-1) .$$

We can now translate any program  $P$  over the natural numbers into the corresponding recursive program  $P'$  and show that  $P'$  terminates by simply proving the relation

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<sup>\*/</sup> Given that  $0, 1, -, +, =$  have their usual meaning.

$$\forall x[\underline{\text{num}}(x) \subseteq \underline{\text{num}}(f_{P_1}(x))] .$$

In other words,  $f_{P_1}(x)$  is defined and its value is a natural number, whenever  $x$  is a natural number.

(B) Equivalence

It should be quite clear at this point that equivalence of two recursive programs is no more difficult to prove than the other properties. Consider, for example, the two recursive programs over the natural numbers

$$P_7 : F(x) \Leftarrow \underline{\text{if}} \ x = 0 \ \underline{\text{then}} \ 1 \ \underline{\text{else}} \ x \cdot F(x-1) \ ,$$

and

$$P_8 : G(x,y,z) \Leftarrow \underline{\text{if}} \ x \leq y \ \underline{\text{then}} \ z \ \underline{\text{else}} \ G(x,y+1,(y+1) \cdot z) .$$

We want to show that

$$\forall x[f_{P_7}(x) \equiv g_{P_8}(x,0,1)] .$$

Note that both  $f_{P_7}(x)$  and  $g_{P_8}(x,0,1)$  computes  $x!$ , but quite differently:  $f_{P_7}(x)$  is 'going down' from  $x$  to 0, while  $g_{P_8}(x,0,1)$  is 'going up' from 0 to  $x$ . This explains why a "direct" computational induction fails in this case.

However, if we consider the predicate  $x > y$  over the natural numbers to be characterized by the least fixpoint  $ge(x,y)$  of the recursive program

$$M(x,y) \Leftarrow \underline{\text{if}} \ x = y \ \underline{\text{then}} \ \text{true} \ \underline{\text{else}} \ M(x,y+1) \ ,$$

we can show by computational induction that

$$\forall x,y[ge(x,y) \subseteq [f_{P_7}(x) = g_{P_8}(x,y,f_{P_7}(y))]] .$$

Then, in particular, for  $y = 0$  we get

$$\forall x [\underline{g}(x,0) \subseteq [f_{P_7}(x) = g_{P_8}(x,0,1)]] ,$$

i.e., for every natural number  $x$ , either both  $f_{P_7}(x)$  and  $g_{P_8}(x,0,1)$  are defined and equal, or both are undefined.

The proof is by computational induction with

$$\Phi(F) : \forall x, y [F(x, y) \subseteq [f_{P_7}(x) = g_{P_8}(x, y, f_{P_7}(y))]] .$$

It is clear that  $\Phi(f^0)$  holds. So, we assume that  $\Phi(f^i)$  holds and show that  $\Phi(f^{i+1})$  holds, i.e.,

$$\forall x, y [f^{i+1}(x, y) \subseteq [f_{P_7}(x) = g_{P_8}(x, y, f_{P_7}(y))]] ,$$

or in other words

$$\forall x, y [ \text{if } x = y \text{ then true else } f^i(x, y+1) ] \subseteq [f_{P_7} = g_{P_8}(x, y, f_{P_7}(y))] .$$

The proof proceeds easily by distinguishing between the two cases where  $x = y$  and  $x \neq y$ .

- (a) If  $x = y$  we get  $\forall x [ \underline{\text{true}} \subseteq_{x f_{P_7}} = f_{P_7}(x) ]$ , which clearly holds.
- (b) If  $x \neq y$  we get  $\forall x, y [ f^i(x, y+1) \subseteq [f_{P_7}(x) = g_{P_8}(x, y, f_{P_7}(y))] ]$ .

Using the definitions of  $f_{P_7}$  and  $g_{P_8}$  we get

$$\forall x, y [ f^i(x, y+1) \subseteq [f_{P_8}(x) = g_{P_8}(x, y+1, f_{P_7}(y+1))] ] , \text{ which holds}$$

by the induction hypothesis.

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