

December 1985

Report No. STAN-CS-86-1093

Also numbered KSI-85-54

A General Reading List for Artificial Intelligence

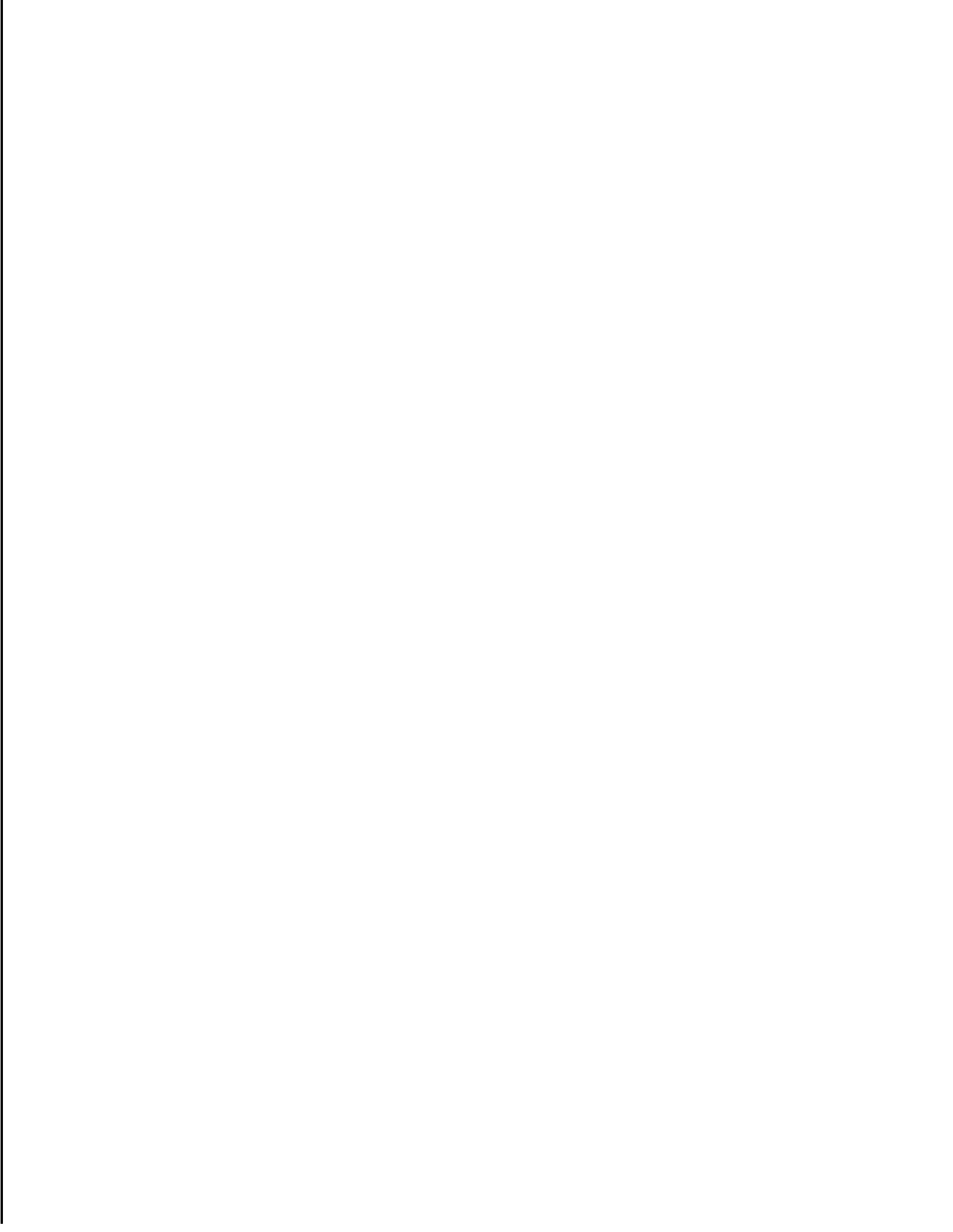
by

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This work was funded in part by the *following* contracts and grants: *DARPA N00039-83-C-0136, NIH/SUMEX RR-00785-12, NASA-AMES NCC-2-274, Boeing Computer Services W266875, NSF IST-8312148*, and a gift from **Lockheed**. Devika Subramanian *is supported* by an IBM Graduate Fellowship.

KSL-85-54

revised December **1985**
first draft April 1985

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This reading list is based on the syllabus for the course CS229b offered in Winter 1985. This course was an intensive 10 week survey intended as preparation for the 1984-85 qualifying examination in Artificial Intelligence at Stanford University.

Preface

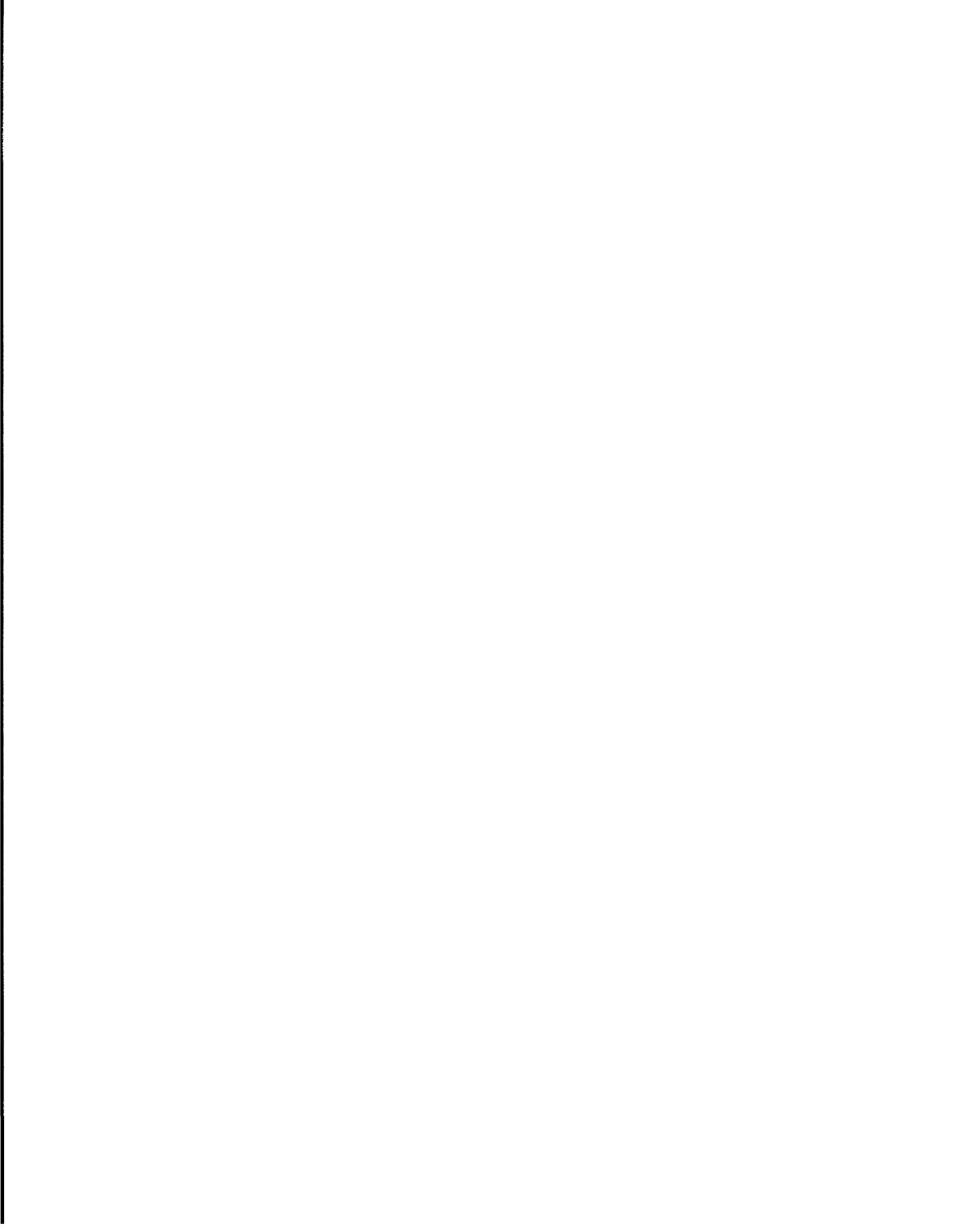
Preface

In the 1984-85 academic year, we offered a seminar to Ph.D. students studying for the qualifying examination in AI in the Computer Science Department at Stanford. Since the intent was to survey nearly all of AI and highlight key issues, the annotated reading list may be helpful to others who are getting started in AI. We organized the readings in ten topics, corresponding to the ten weeks the seminar ran.

The first section, Introduction to AI, is a list of books and articles that will help in obtaining an understanding of the enterprise of AI. Topics 2 through 5 form part of a theoretical core for AI. They set the stage for understanding issues in the subsequent, areas. Topics 6 through 9 are specialized topics in which AI research has been driven by specialized applications. The final section, Advanced Topics, covers many important current issues which are not properly included in the earlier, more basic sections.

This reading list is graded and annotated. For each topic, we present basic reading drawn for the most part from the AI Handbook. Required papers are taken from the Webber-Nilsson collection of **AI** readings. Recommended readings serve both to introduce new research (post 1982) and also reinforce material covered sketchily in the basic reading.

This compilation of the reading list is an ongoing effort. Comments and suggestions on this are very welcome for future editions.



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1 Introduction to AI

This set of readings will help obtain an understanding of what Artificial Intelligence is and provide a historical perspective. These may be read along with the reading on the other topics. These are not pre-requisites for any of the other readings in this syllabus. For current discussion on the nature of AI see the reading list on Advanced Topics in this syllabus. The opening chapters of AI textbooks by Winston, Rich and McDermott & Charniak, Nilsson & Genesereth are also recommended.

- ***Computers and Thought: Feigenbaum and Feldman, McGraw-Hill, 1963***

Though a bit **dated**, this book is still an important collection of ideas in Artificial Intelligence. Turing's epoch making article "Computing Machinery and Intelligence" is reprinted here. Minsky's "Steps towards AI" contains a research program that asks questions that are important (and are unanswered!) even today. Gelernter's geometry machine and Samuel's checker player are also described here. The dichotomy in AI between those who wish to duplicate human intelligence (and use AI as a vehicle for studying human intelligence) and those who wish to create a machine intelligence (without regard to whether or not it is human) is evident in the organization of this book.

- ***Semantic Information Processing: Minsky, MIT Press, 1968***

This collection mostly contains articles that represent pioneering work on AI, done at MIT in the early and mid-sixties. Included are Raphael's SIR, Evans' geometry analogy program and Bobrow's STUDENT. McCarthy's "Programs with Common Sense" is reprinted here as well as Minsky's thought-provoking "Matter, Minds and Models". The preface is exceedingly well written and is of historical interest.

- ***Artificial Intelligence and Natural Man: Boden, Basic Books, 1977***

A classic. Has an extensive annotated bibliography.

Introduction to AI

- ***Machines who think: McCorduck, Freeman, 1979***

A very interesting (and entertaining) book which traces the history of AI in the United States.

2 Search and Heuristics

Basic Reading

- ***Artificial Intelligence (2nd ed.)*, Patrick Winston, 1984, Addison- Wesley, Chapter 4**

This is a very readable introduction to basic search strategies. The taxonomy of search strategies on Page 88 should help organize the material learnt from Section C of Chapter 2 of the Handbook. The examples presented here are good. It is recommended that you skim through this before you read the presentation in the Handbook and in Nilsson's book.

- ***The Handbook of Artificial Intelligence, 1981, William Kaufmann Inc., Volume 1, Chapter 2***

This is a reasonably well written introduction to the vast literature in search. It gives pointers to most of the important papers in this area. Sections B and C contain basic concepts that should be learnt well. A lighter introduction to material in Section C is in Winston (above). Section C.3 and Chapter 2 of Nilsson's text are mutually redundant, so are Section C.4 and Chapter 3 of Nilsson's text. Details of systems in Section D are unimportant but you do need to know which search strategy was used and why.

- ***Artificial Intelligence, Elaine Rich, 1983, McGraw Hill, Chapters 2,3 and 4***

Sections 2.1, 3.6 through 3.7, and all sections in Chapter 4 are relevant.

- ***Principles of Artificial Intelligence, N.J. Nilsson, 1980, Tioga Publishing Co., Chapters 2 and 3***

There is a clear, detailed discussion of search strategies here. It is about 50 pages long, but familiarity with these methods is a prerequisite for planning, theorem proving, expert systems etc. You may skip Section 3.3 of Chapter 3. See remark on Handbook Chapter 2 above regarding overlap with this book.

Search and Heuristics

Required papers .

Readings in *artificial intelligence, Nilsson and Webber, Chapter 1*

. The five papers in this chapter introduce some of the important research issues in search.

- ***On Representations of Problems of Reasoning about Actions : Saul Amarel, 1968***

Amarel's paper is a classic study on how shifts in problem representation can drastically reduce the size of the search space. Recent work at CMU (Korf 80) and Rutgers (Riddle 84) attempt to pursue the intriguing ideas presented here. This paper **occurs** again in this reading list under Knowledge Representation since this discusses the automation of representation shifts. For now, you should be familiar with examples of successive reformulations which reduce search effort in problem solving.

- ***A Problem Similarity Approach to Devising Heuristics : John Gaschnig, 1979***

The use of heuristic estimating functions for controlling search raises the question of how to obtain these functions. John Gaschnig's paper suggests an interesting approach laying a nice foundation for future work in this area. Short and well-written paper. Compare with the learning of heuristics **a la Lenat**.

- ***Optimal Search Strategies : William Woods, 1982***

Woods's paper views recognition as search. Instead of searching for a minimal **cost** path to a goal state, Woods seeks the final state with the highest score (regardless of the the cost of the path to the state). The shortfall method for scoring states is an instance of the **A*** algorithm. The density method, which is also optimal, is interesting because it is not an instance of **A***. This paper ends with a comparison with the strategies used in other speech understanding systems, which **can be read** when we address the topic of Speech Understanding Research. The basic idea behind the shortfall and density methods must be learnt but the details are unimportant.

- ***Consistency in Networks of Relations : Alan Mackworth, 1977***

Mackworth's exceedingly clear paper provides a very good introduction to constraint

satisfaction and network consistency algorithms. The style of presentation is worth noting as well as the contents, which are fundamental to understanding more recent work in this area. The three maladies of backtracking and their proposed remedies should be reasonably well understood. Think also about the use of constraints in AI systems [Steele 78].

- **The B* Tree Search Algorithm : a Best First Proof Procedure : Hans Berliner, 1979**
Much of the early work in search (and AI) was done in the context of game playing programs. Chess has posed particularly challenging problems here. Berliner's paper proposes the B* algorithm for searching game and proof trees. The main idea in this algorithm is the use of two bounds to cut off search - the optimistic bound used by the A* algorithm as well as a pessimistic bound. You should be able to explain this algorithm with an example.

Recommended Reading

This is a compendium of more recent work in search. For work before 1982, the handbook has all the pointers. It may not be necessary to read all that material if you are familiar enough with the presentation in the handbook.

- **Nature of Heuristics I : Doug Lend**

AI Journal, Vol 19, 1982

This is the first article in the three part series on heuristics. It introduces the field of heuristics and forms the basis for the results reported in the second and third articles referenced below.

- **Special AI Journal issue on Search and Heuristics**

Vol 21, Nos 1-2, March 1983

The stout-hearted can begin directly with the 10 articles here that are representative of current research in this area. The general theme that knits these papers together is the quest for understanding the workings of heuristic knowledge. The following

papers in this collection are recommended. The rest of the papers in this collection are on performance analysis of various search algorithms and game playing strategies. It is recommended that you read the abstracts or skim through the contents.

Search and Reasoning in Problem Solving : Herb Simon, 1985

This paper contrasts the search metaphor and reasoning metaphor in problem solving. Worth reading in full.

Nature of Heuristics II and III : Doug Lenat, 1983

These describe research aimed at automating the process of learning by discovery in various fields, including heuristics. Skim through them with special attention to the examples.

• *Knowledge vs Search : A Quantitative Analysis using A* : J. Pearl*

AI Journal, Vol. 20, No.1 ,1983

Knowledge and search are two major commodities that fuel and propel AI programs. We have a qualitative understanding of the interaction between the two (cf. Dendral). This paper is an attempt to quantify the knowledge-search tradeoff in the context of heuristic search algorithms. It is a mathematical exposition of the dependence on the average number of nodes expanded by A* on the accuracy of its heuristic estimate. Think about the problems of doing this sort of analysis in the context of a heuristic program, say Dendral.

• *Strategies in Heuristic Search : M. Georgeff*

AI Journal, Vol 20, No.4, 1983

Real valued heuristic functions have been extensively used as a means of constraining search in combinatorially large problem spaces. An alternative approach called strategic search is examined, in which heuristic information is expressed as problem specific strategies. These are intended to guide one toward a goal state, but there is no guarantee for success. Admissible algorithms **using** strategy **search** are presented.

Strategy search in hierarchically organized problem spaces and **meta** level strategies to guide application of base level strategies are also considered. Extremely interesting, look at some examples in the paper.

- **1976 ACM Turing Award Lecture by Simon and Newell**
CACM Vol 19, pages 119-126

“Computer Science as empirical inquiry – symbols and search”.

Emphasizes the primacy of search in AI. Historical interest.

- **Constraints : Guy Steele, Jr. and Gerry Sussman**
MIT-AI Memo 502, 1978

Constraint propagation is introduced here. Read and compare this with problem solving by search.

- **Generalization as Search : T. Mitchell, 1982**

Nilsson and Webber collection : Chapter 5, Article 8

The generalization problem in systems which learn from examples is presented in the search framework. Observe the mileage we get when we cast problems into the search perspective. This should start one thinking about search in relation to other areas in AI.

3 Knowledge Representation

Basic Reading

- ***Principles of Artificial Intelligence, N.J. Nilsson, 1980, Tioga Publishing Co., Chapters 1,4,9,10.3***

Chapter 1 introduces production systems with lots of examples. Chapter 4 introduces predicate calculus as a knowledge representation language in AI. The following concepts should be learnt well : unification, pattern matching, converting to CNF, resolution (just the definition, for now), validity and satisfiability of a wff, completeness and soundness of a set of axioms and inference rules. **Read** section 4.3 carefully to get a sense of how **Nilsson** intends predicate calculus to be used in AI (also section 10.3 is relevant here).

Chapter 9 introduces units and has a very extensive treatment of semantic nets and operations on them. The concepts of property inheritance and procedural attachments are very important. Read Section 9.6 to get a historical perspective on the semantic net formalism and also a comparison with other formalisms. Do exercise 9.5 at the end of the chapter with respect to every subarea of AI.

- ***The Handbook of Artificial Intelligence, 1981, William Kaufmann Inc., Volume 1, Chapter 3***

Skim through Section A. For the procedural/declarative controversy see [Winograd 75] below. Skim also through Section B. Read Section C carefully to get a sense of the following for each representation formalism.

- Example of a use of the knowledge representation formalism.
- The operations that can be performed on it.
- Disadvantages and advantages of the formalism with an example of a case where it would be hopeless and where it is extremely useful.

– Current research issues.

Supplement the material on semantic nets with the more comprehensive treatment in Nilsson. Production systems are well explained in the Davis and King article that is recommended. Semantic primitives are not a representational formalism *per se*, but could form the basis of one. For more on this read Chapter 4 of the Handbook. The original paper on frames by Minsky is worth looking over, it has ideas that could be pursued for further research. The main utility of the Handbook is the large number of pointers it provides to the rather extensive literature on knowledge representation. It is not necessary to follow up on all these, except for the ones listed under recommended reading.

- **Artificial Intelligence (2nd ed.), Patrick Winston, 1984, Addison-Wesley, Ch 2 and 8**
Read pages 21-24 and pages 41-42 of Chapter 2 only if you are hard pressed for time. Look at the desiderata for good representation on Page 23. The rest of the chapter consists of examples highlighting the issues raised there. Read Chapter 8 after you have covered Section C of the Handbook. This will help in organizing the material that is covered there with some very good examples.

Required papers

Readings in Artificial Intelligence: Nilsson and Webber

- **On Representations of Problems of Reasoning about Actions : Saul Amarel, 1968**
Several successive reformulations of the familiar missionaries and cannibals problem lead to improved problem solving efficiency. The kinds of reformulations hinted at here have not yet been automated. What sorts of knowledge do we need to do reformulation in general? Do we need a theory of representations to do this? This is still an active area of research. Read the conclusions of this article carefully, almost every paragraph contains an idea worth exploring as a dissertation in AI. Think of an example of incremental reformulations in a domain other than the highly artificial one of the

missionaries and cannibals. Current work by Riddle [Riddle 84], Korf [Korf 82], Lowry [Lowry 84] attempts to solve some of the problems in this area of representation shifts.

- ***The Logic of Frames : Patrick Hayes, 1979***

Several alternatives to logic as a representation language have been **proposed at various** times. Most have turned out to be syntactic variants of first order **logic rather than** fundamentally different systems. Many of these elevate important implementation details like indexing to the level of syntax of the language. This **paper shows how** a frame based system can be interpreted as a system of first order logic. **Contrast** this with the section on Page 21 of Winston's book (2nd ed) entitled : ***Theoretical equivalence is different from practical equivalence.***

- Recommended Reading

- ***Extending the Expressive Power of Semantic Nets : Schubert***

AI Journal, Vol 7, 1976

The semantic net notation is extended for the representation of logical **connectives**, quantifiers, time and modal operators. Look at the examples in this paper. As **an** exercise : Represent the transitivity axiom using semantic nets.

- ***Some Problems and Non-problems of Representation Theory : P.J. Hayes***

British Computer Society, AISB summer conference, 1974

This is Hayes' perspective of what is and is not important in **Knowledge Representa-**tion. Recommended only for people who think they might **do a thesis in Knowledge** Representation.

- ***Programs with Common Sense : John McCarthy***

In Minsky's Semantic Information Processing, MIT Press, 1968

Describes the Advice-Taker. Historically important. Asks the question: what are the reprcsentational and reasoning requirements for a common sense **problem solver?**

- ***The Second Naive Physics Manifesto : P. J. Hayes***

In Formal theories of the Commonsense World, edited by Jerry Hobbs and Robert Moore, Ablex Press, 1985

Hayes suggests a program of research for the construction of a formal theory of the commonsense world : he identifies 'clusters' in our commonsense knowledge and indicates an order in which to tackle them. Very valuable for those intending to do research in this area.

- ***KRYPTON : Integrating Terminology and Assertion : Brachman, Fikes and Levesque***
In the proceedings of AAAI-88

A hybrid representation system is presented that combines in a completely integrated fashion a frame based description language and an assertional component that uses ϵ first order resolution theorem prover. An update of this paper occurs in the proceedings of IJCAI-85.

- ***A Framework for Representing Knowledge : Minsky***

MIT-AI memo 594, 1974, also in the Psychology of Computer Vision, edited by Patrick Winston, MIT Press, 1975

The classic paper which started off work on frames. Skim through this paper, it has several interesting ideas. The appendix has a critique of the logic approach to Knowledge Representation.

- ***Frame Representations and the Procedural/Declarative controversy : Winograd***

In Representation and Understanding, edited by Bobrow and Collins, Academic Press, 1975

Highly recommended for a clear understanding of this famous controversy.

- ***In Defense of Logic : P. J. Hayes***

In the Proceedings of IJCAI5, 1977

Recommended only for those with a deep interest in Knowledge Representation. Indicates that logic is the only knowledge representational formalism with a very well specified semantics in spite of its spartan syntax.

- ***Distinctions and Confusions : A Catalogue Raisonne : Israel, Brachman***
In the Proceedings of IJCAI7, 1981

A tongue in cheek paper clarifying the issues on the semantic nets vs predicate calculus debate. Worth reading in full.

- ***An Overview of Production Systems : Davis and King***
in Machine Intelligence 8, 1977, edited by Elcock and Michie
Edited and Reprinted in Buchanan and Shortliffe(eds), Rule Based Expert Systems

The definitive work on production systems. Explains what they are, and highlights when they are useful and when they are not.

- ***Semantic Net Representations in Rule Based Inference Systems: Duda, Hart and Nilsson***
in Pattern Directed Inference Systems

This explains the knowledge representation mechanism in PROSPECTOR.

- ***SIGA RT special issue on KR, Vol. 70, 1980, edited by Brachman and Smith***

This was a Knowledge Representation questionnaire sent out to AI practitioners of the day. The hope was that the editors would compile a perspective(s) which emerged from that survey. What resulted was more like the Tower of Babel. The questions are worth noting. Skim judiciously through the responses!

- ***Vision : Marr***

Pages 19-29 have **Marr's** perspective on knowledge representation which is quite different from the conventional view in AI. These few pages are highly recommended.

- **Reflection and Semantics in a Procedural Language : Brian Smith**

MIT- TR-272, 1982

This is Brian Smith's PhD thesis describing the construction of a reflective Lisp called **3-Lisp**. It is extremely long. The introduction and the first two chapters are highly recommended.

- **Formal Theories of the Commonsense World : Hobbs and Moore, Ablex, 1985**

This is a collection of work that focuses on **what** an intelligent agent needs to know to make its way in the real world. All the papers here are worth reading. Some that are especially interesting are

- Naive Physics I : Ontology of liquids : P.J. Hayes

The tricky problems encountered in representing and reasoning with our common sense knowledge of liquids are described here.

- A Qualitative Physics based on Confluences : de Kleer and Brown

Qualitative differential equations are used to model reasoning about the behavior of complex physical systems. This will allow a robot in **the real world to make** quick decisions about the outcome of events on the basis of incomplete **qualitative** information.

- **Readings in Knowledge Representation : Brachman and Levesque, Morgan Kaufmann Publishing Co., 1985**

An excellent collection of readings in knowledge representation, many of **the selections** there are in this **list**.

4 Planning, Problem Solving and Automatic Programming

Basic Reading

- ***Artificial Intelligence (2nd ed.)*, Patrick Winston, Addison-Wesley, 1984, Chapter 3,5,6,7**

A recommended order for going through these chapters is **6,7,5,3**. Chapter 6 is on problem solving paradigms. The most important section is the one on Generate and Test. Chapter 7 introduces resolution proofs, planning in the blocks world and problem solving by constraint propagation. This exposition is not at a very high level, but you have to know at least this much before you tackle the rest of the readings, also the examples given here are invaluable for understanding the material. Chapter 5 introduces control metaphors in problem solving. The section on means-end analysis and GPS is very well written. You may skip that section in the Handbook if you read this treatment. Chapter 3 is on constraint propagation. This book does not cover Automatic Programming. It has a limited coverage of planning as indicated above. Good exposition of problem solving paradigms.

- ***The Handbook of Artificial Intelligence, Volume 3*, William Kaufmann Inc., 1982, Chapter 15, 10, 11 B and C**

Chapter 15 is on planning and problem solving. The four systems STRIPS, AB-STRIPS, NOAH and MOLGEN should be learnt well. In case you get lost in the details of these systems, read Earl Sacerdoti's (see below) excellent review of problem solving tactics, which will help form a unified perspective in which to view these systems. GPS is covered in Chapter 11. section B. Skim through this if you have read Winston's exposition. Chapter 11, section C is on the Hayes-Roth and Hayes-Roth opportunistic planner. Chapter 10, sections A, B, C.1, C.4, C.5 and **C.8** are relevant here. We will cover all Automatic programming work which can be viewed from the planning perspective - i.e transforming high level **specifications** into a program in a

given target language. Synthesizing programs from examples (this involves induction) will be covered under Learning (but note Manna and Waldinger's synthesis by deduction) .

- ***Principles of Artificial Intelligence, N.J. Nilsson, Tioga Publishing Co., 1980, Chapters 7 and 8***

These two chapters cover STRIPS, ABSTRIPS and RSTRIPS in gory detail. Read them after the Handbook sections. Do the exercises at the end. They will stimulate thinking on the various issues in planning.

Required papers

From Readings in Artificial Intelligence : Webber and Nilsson, 1982

- ***Application of Theorem Proving to Problem Solving : Green, 1969***

Indicates how a purely deductive approach based on first order logic can be used to generate robot plans. Can be seen as an attempt to build McCarthy's Advice Taker (see readings for Knowledge Representation). The answer extraction method is important. Nilsson's text explains this also. The examples in the Green paper are to be noted. Think about the problems with this approach to problem solving.

- ***The Frame Problem and Related Problems in AI : Hayes, 1978***

Studies the frame problem which arises in the context of representation of actions. This paper is somewhat hard to read. It presents all the solutions to the frame problem that have been proposed in literature in a unified framework.

- ***Learning and Executing Generalized Robot Plans: Fikes, Hart and Nilsson, 1972***

This is one of earliest systems that dealt with execution monitoring. Also note how STRIPS deals with the frame problem.

- ***Achieving Several Goals Simultaneously : Waldinger, 1977***

This well written paper talks about goal regression, a method similar to passing a

condition back over an operator in program verification. Chapter 8 of Nilsson's text is on RSTRIPS which uses goal regression.

- ***Planning and Meta-Planning : Stefik, 1981***

This explains hierarchical control of planning. Contrast the ideas here **with those in** the meta-level architecture proposed by Genesereth and Smith (reading on **Advanced Topics**). Stefik has another paper (see below) where he expounds **the other key idea** in MOLGEN – explicit representation of the interaction between **subproblems as constraints** and constraint posting as a method of communication between the different levels **of planning**.

- ***An Experiment in Knowledge-Based Automatic Programming : Barstow, 1979***

What you should get out of this paper, for now, is a sense of how the program **synthesizes** problem can be tackled in the production system framework. This **work has been quite** successful in the real world.

- ***Patterns and Plans in Chess : Wilkins, 1980***

The program PARADISE which generates chess plans using rule **based representations** of expert knowledge in chess tactics is described here. Read section 12 (**comparison** with robot planning) carefully.

Recommended Reading

- ***Problem Solving Tactics : Earl Sacerdoti***
In AI magazine, 1981

This is a nice overview of planning and problem solving techniques. **Supplementary** reading to the presentation in the Handbook.

- ***Sciences of the Artificial : Simon***
MIT Press, 1969

This little book has four of Simon's most beautiful essays. Simon's art is **in the second**

essay. The piece entitled “The architecture of complexity” is highly recommended. Simon also speculates on how research in representations should **proceed**.

- ***Planning with Constraints – Molgen:Part 1 : Stefik***
in AI Journal Vol 16, No 2, 1980

This is the constraint posting article referred to previously in this document.

- ***Design of a Programmer ‘a Apprentice : Rich and Shrobe, 1979***
In AI: An MIT Perspective, edited by Winston and Brown, 1979

This is an early description which indicates the input-output behavior of a Programmer’s Apprentice and the kinds of reasoning mechanisms and programming knowledge needed to support it.

- ***Planning for Conjunctive Goals : Dave Chapman, 1985***
MIT-AI- TR-802

This is a rational reconstruction of previous work on domain-independent **conjunctive** planning : the state of the art is distilled into the algorithm TWEAK that has been proved to be correct and complete.

- ***Reasoning about plans : Drew McDermott, 1985***
In Formal Theories of the Commonsense World, edited by Hobbs and Moore, Ablex, 1985

A theory of actions is constructed in the framework of a previously developed **ax-**iomatization of time. Planning is viewed as a kind of deduction. Critical aspects of actions like **subtask**, success, failure and feasibility are formalized.

- ***A Model of Naive Temporal Reasoning : Allen and Kautz, 1985***
In Formal Theories of the Commonsense World, edited by Hobbs and Moore, Ablex, 1985

A formal account of time based on intervals is described. This allows reasoning **about**

time at various levels of granularity for problem solving and story understanding.

- **Qualitative Process Theory : Forbus, 1985**

MIT AI Lab PhD thesis, 1985

The knowledge and reasoning mechanisms needed to support commonsense process understanding is presented here.

- **A Perspective on Planning : Stun Rosenschein**

In the Proceedings of AAI 84

The **BDI** model is described here. Planning becomes intention management in this **model**.

Also see papers by Balzer, Dershowitz, Smith, **Manna, Kant and Barstow in the proceedings** of IJCAI-85 to get a feel for recent research. Steier, Kant **and Newell [Kant and Steier 85]** work on algorithm design methods. Barstow's papers address practical automatic **programming issues**.

5 Deduction and Inference

Basic Reading

- ***The Handbook of Artificial Intelligence, Volume 3, William Kaufmann Inc., 1982, Chapter 12***

The overview is well written and should be read carefully. For details on **the historical** evolution, read the Loveland article in the recommended readings below. The **reso-**lution rule of inference is discussed very briefly in Section B. Supplement it **with** the material in Section 5.2 of Nilsson's text. Non-resolution theorem **proving should be** familiar to those who have read Manna's MTC text. The interesting thing to note here are the heuristics built into Automatic Theorem Provers (**ATPs**). A **more complete** list is in the Bledsoe article (below). The Boyer-Moore theorem prover is **important**. The brief overview on non-monotonic **logics** is a good introduction to newer research in the **area**(covered in the Recommended Reading below). It is a hot topic of research now. Logic programming is better covered in Kowalski's book (below).

- ***Principles of Artificial Intelligence, N.J. Nilsson, 1980, Tioga Publishing Co., Chapters 5 and 6***

Relevant sections here are 5.2 [Resolution strategies with examples], 5.3 [**Simplification** - note especially procedural attachments which are discussed further in **Wehrauch's** article], 5.4 [Answer extraction]

Chapter 6 is long and the sections on forward and backward deduction systems can be skimmed. It is useful to go through the control strategies. The bibliographical remarks at the end of Chapter 6 are very important for a historical perspective.

Required papers

from ***Webber and Nilsson's Readings in Artificial Intelligence***

- ***Non-Resolution Theorem Proving : Bledsoe, 1977***

Bledsoe (a convert from resolution theorem proving) gives alternatives to resolution in ATP. For each note the main idea along with an example. Get a sense as to why each of the problems mentioned in Table 1 constitute challenges for present day ATP's. Read the bibliography to learn names of people in this enterprise.

- o ***Using Rewriting Rules for Connection Graphs to Prove Theorems : Chang and Slagle, 1979***

This is an attempt to speed up resolution theorem proving. Chang and Slagle pre-compile potential matches between clauses in their connection graph. Reading pages 219-222 of Nilsson before this might help. The exposition here is very clear, however.

- ***On Closed World Databases : Ray Reiter, 1978***

The consequences of the closed world assumption in query evaluation in data bases is examined here. Examples and statements of theorems are important. Proofs are not necessary.

- ***A Deductive Approach to Program Synthesis : Manna and Waldinger, 1980***

Program synthesis cast in a theorem proving framework. Combines techniques of unification, induction (cf. Boyer Moore theorem prover) and transformation rules (cf. PECOS) into a unified framework. See how they synthesize recursive programs.

- ***Prolegomena to a Theory of Mechanized Formal Reasoning : Weyhrauch, 1980***

The important concepts here are semantic attachments and reflection. Semantic attachments provide a way of realizing the benefits of procedural and declarative representations in the same framework. Reflection principles and meta-theories are covered in greater detail in Weyhrauch's paper in the 5th Conference on Automated Deduction Systems (Springer-Verlag Lecture notes in CS, no. 138).

- Subjective Bayesian **methods** for **Rule Based Inference Systems** : **Duda, Hurt and Nilsson, 1976**

This is a short paper and the details here are important. Read the relevant sections of the **Buchanan/Duda** article (below) before you read this.

Recommended Reading

The readings below attempt to cover default and probabilistic reasoning, circumscription, NM **logics**, resource limited reasoning, logic programming. Additions to this set are welcome.

- **Automated Theorem Proving: a Quarter Century Review** : **Loveland**
in AMS Contemporary Mathematics v.29 "Automated Theorem Proving: After 25 Years" edited by **Bledsoe and Loveland**

This is the Loveland overview referred to above.

- **Principles of Rule Based Expert Systems** : **Buchanan and Duda**
HPP-82-14

The sections on the handling of uncertainty in expert systems are relevant for now. It might be useful to read this before the **Duda** article in the required **reading**.

- **On Reasoning by Default** : **Reiter**
in TINLAP-C

Very short and highly readable introduction to default reasoning. Highly **recommended**.

- **Computation and Deduction** : **P.J. Hayes**
in the Czech. Acad. of Sciences proc., 1978

Argues for consideration of all computation as controlled deduction.

- **Logic for Problem Solving** : **Kowalski, Elsevier, 1979**

A well written, though wordy introduction to logic programming. There are **examples**

and issues to be gleaned from here. Compare this with PLANNER.

- **Algorithm = Logic + Control : Kowalski**

in CACM, Vol 22, No. 7, pages 424-436

Perspective : separates control information **from** logic information in programming (i.e separate the **what from the how**).

- **AI journal special issue on Nonmonotonic Logic, Vol 13, nos 1:2**

This describes current efforts on non monotonic **reasoning**. **McCarthy's circumscription** paper (the follow up paper is listed below), **McDermott and Doyle's "Non-monotonic logic I"** (Moore's correction to **it is below**), **Reiter's paper on default logic**, Terry Winograd's article on resource-limited **reasoning as well as Wehryrauch's article** here are worth **reading**.

- **Semantical Considerations on Nonmonotonic Logic : Moore**

SRI Tech note 284, June 83

Corrections to the McDermott and Doyle version of Nonmonotonic **logic**.

- **Circumscription : McCarthy**

SAIL tech report, October 1989

Generalization of the 1980 paper, has a cleaned up version of the basic **formalism**.

- **Default Reasoning as Likelihood Reasoning : Rich**

in the Proceedings of the AAAI-89

Integration of default reasoning with probabilistic **reasoning**.

- **Probabilistic Logic: N.J. Nilsson**

In the AI Journal (in press)

- **Automated Reasoning: Introduction and Applications, Wos, Overbeek, Lusk and Boyle, Prentice- Hall, 1984**

The preface has a reading guide. Chapters **1** thru **5** are introductory and can be skipped. Resolution strategies are presented with examples in Chapters **6** and **7**. Chapters **9** and **10** are highly recommended : they indicate how automated reasoning can be used to do discovery in mathematics. Chapter **16** indicates open problems in this area.

6 Expert Systems

The objective here is to learn about expert systems and the principles **they are based on** before studying the details of individual systems. It is recommended that the basic reading be done in the order given.

Basic Reading

- ***Principles of Rule Based Expert Systems : Buchanan and Duda, 1982***

HPP-82-14

This paper discusses key issues in expert system design: representation, inference **and** uncertainty management. It has a large number of pointers to specific expert systems which one should follow up in the Handbook or in the book ***Building Expert Systems***. It is primarily about rule based expert systems, though other representational frameworks are briefly discussed. The interested should look at the recommended readings from the MYCIN book which cover this exhaustively. Section 5 is extremely important for a well rounded understanding of expert systems. It lists **all** the key concepts and indicates the range of problems for which expert systems are useful.'

- ***New research on expert systems : Buchanan, 1981***

HPP-81-1

The current state of the art and directions for future research are presented here. Lessons **from** early work and characteristics of domains for which present-day expert systems are suited are also indicated. There are many pointers to recent work **on** extending the capabilities of expert systems.

- ***Expert Systems : Paul Harmon and David King, Wiley, 1985, Chapter 9, 10***

Chapter 9 is an excellent review of the early expert systems and complements the AI Handbook treatment(below). Chapter 10 covers the more recent systems **R1**, **MOLGEN**, The **DIPMETER** Advisor and **EXPERT**(some of these are not discussed in the AI Handbook).

- ***Building Expert systems, Hayes-Roth, Waterman and Lenat, Addison- Wesley, 1988, Chapters 1,2,3,4,5,7,8***

This book is a how-to book and is quite easy to read. Chapters **4,5,7,8** are recommended in particular. Lots of open problems remain in the areas addressed by Chapters 7 and 8.

- ***The Handbook of Artificial Intelligence, Volume 2, William Kaufmann Inc., 1982, Chapters 7,8,9***

All the overviews should be read carefully. The overview section of **Chapter 7 could be** supplemented with the first chapter of “Building Expert Systems” **especially for the** historical evolution of expert systems. The details of the individual expert **systems in** these chapters should be read with a view to answering some of the questions below.

- Associational questions – who, when, where, why.
- Main ideas – representation, control, validation etc.
- Concept-wise indexing – which systems explored concept X ?
- A canonical example of the system’s functioning which brings out its **limitations** and strengths.
- Current status of the system.

The original reference for Dendral is in the Required papers below. The **Meta- Dendral** reference is in the reading list for Learning. The original reference for Crysalis is **Alan** Terry’s thesis (HPP-83-19). For Macsyma, you could read Moses’ Macsyma primer [Mathlab Memo 2, MIT]. To get more about symbolic integration read [Moses **1971:** Symbolic integration, the stormy decade: ACM **14**, pp 548-560]. There **are two papers** on Prospector in the Webber-Nilsson collection – one detailing the model design **aspect** and the other explaining the **probabilistic** belief updating scheme **used. RI is not** covered here, so read the AI magazine articles on this subject. **It** is important to **not**

lose sight of the issues when wading through the details of the individual systems. This caveat extends to the whole of this reading list. Preparation of time lines and short summaries of systems while reading about them is highly recommended.

Required papers

Readings in AI : Webber and Nilsson

• ***Consultation Systems for Physicians : Ted Shortliffe, 1980***

This proposes design criteria for clinical expert systems (like MYCIN) to increase their acceptability among physicians. Human engineering issues are important in the design of an expert system because the end users are often humans. This article talks about the specific problems (mechanical, epistemological and psychological) that arise in the design of medical computing systems. A revised version of this article occurs as Chapter 5 of [Clancey84].

• ***An Experiment in Knowledge-Based Automatic Programming : David Barstow, 1979***

PECOS forms a component of a full fledged and working AP environment at Kestrel Institute. Read this to get some details on the kinds of knowledge encoded in PECOS. Also note how PECOS derives the well-known trick of computing the intersection of two linked lists in linear time.

• ***Dendral and Meta-Dendral : Their Applications Dimension : Buchanan and Feigenbaum, 1978***

Very important paper. Has succinct descriptions of Dendral and Meta-Dendral.

• ***Model Design in the PROSPECTOR Consultant System for Mineral Exploration : Duda, Hart and Nilsson, 1979***

This is a description of the PROSPECTOR system which uses inference networks of geological assertions and the Bayesian propagation formalism to model the judgmental reasoning of economic geologists. The model design process illustrates the transfer of knowledge from human experts to **computational** formalisms.

- ***The Hearsay II Speech- Understanding System : Erman et al., 1980***

This is a good example of application driven AI research that led to the **development** of a new problem solving architecture. The **BB1** architecture [Hayes-Roth84] is a substantially extended and generalized version **of** this system.

- ***Interactive Transfer of Expertise : Acquisition of New Inference Rules : Randall Davis, 1979***

One approach to the KA bottleneck is explored here : this is to partially **automate the** role of the intermediary knowledge engineer, by giving the system knowledge about the form of the rules and making it acquire knowledge from the expert in the context of an error in the reasoning made by the **system**.

Recommended Reading

- ***Expert Systems: Working Systems and the Research Literature: Bruce Buchanan KSL-85-87***

This is a compilation of work on expert systems **upto** 1985, with an emphasis on systems actually working. The defining characteristics of expert systems **are important**. Also scan the Expert System papers published in the proceedings of **IJCAI and AAAI** in recent years.

- ***Expert Systems : Where are we, where are we going? : Randall Davis in AI magazine 1982***

This article talks about the current state of the art in expert systems and **indicates** the deficiencies in them. It then proposes ways of overcoming them by the use of causal models and reasoning from first principles. This is extremely well written **and** it is highly recommended.

- ***ROGET - A KB consultant for acquiring the conceptual structure of expert systems : Bennet***

HPP-83-24

This attempts to attack the most difficult part in the design **of an expert system** - obtaining the vocabulary and inference structure. The approach **is to treat this** problem as a classification problem (Clancey 83) and there are 9 problem classes identified. Only one (for diagnosis) of them is implemented.

- ***Rule Based Expert Systems : Buchanan and Shortliffe***

Addison Wesley, 1984

This is the MYCIN book. Chapters 21-24 cover other representational **frameworks for** expert systems. **A** good introduction to Knowledge Engineering **is in Chapter 7**. **All** you ever wanted to know about uncertainty management in MYCIN is in Chapters 10-13. Chapter 17 expounds on explanation and its role in AI research.

- ***The Epistemology of a Rule-Based Expert System : a Framework for Explanation :***
W. J. Clancey

HPP-81-17

Indicates the shortcomings of the production rule framework for teaching **and expla-** nation. Indicates the kind of knowledge that is embedded in rules that **have to be** made explicit for the purpose of tutoring or explanation.

- ***Maxims for Knowledge Engineering : David Barstow and Bruce Buchanan***

HPP-81-4

This lists some principles (and folklore) in the art and craft of Knowledge **Engineering**.

- ***The advantages of abstract control knowledge in expert system design : William Clancey***

HPP-83-17

Abstract control knowledge makes the design of an expert system **more transparent** and explainable. It also provides a generic framework for constructing **KB's for related** problems in **other** domains. It is a useful starting point for the study of **strategy**. **This**

paper has examples of abstract control knowledge from NEOMYCIN. The difficulties in gathering such knowledge is stressed.

- ***The Blackboard Architecture : a general framework ×□□ Problem solving? : Barbara Hayes-Roth***

HPP-88-38

This is an attempt to define and evaluate the blackboard architecture independent of a particular application. It clearly defines the components of a blackboard system and enumerates the assumptions behind these components. This is of relevance here because it provides a framework for bringing many knowledge sources to bear on a problem. This is more flexible than a rule based expert system, but for computational efficiency we need compilation (cf HARPY).

- ***Rule based Understanding of Signals: Nii and Feigenbaum***

In Pattern Directed Inference Systems, edited by Waterman and Hayes-Roth

This is a signal processing application that uses the blackboard architecture. It is the root of the AGE project at Stanford (Nii).

- ***R1 : A rule based configure? of computer systems: J. McDermott***

AI Journal, September 82

The R1 paper. R1 is an expert system that configures VAXen for DEC. It is a production system that uses forward chaining and is probably the most widely used expert system in existence.

- ***An overview of Meta-Level Architecture : Genesereth and Smith***

MRS is a realization of the Advice Taker (McCarthy58) with explicit control of reasoning. It is a logic based system that provides a variety of representation and inference methods for the implementation of expert systems.

- ***Heuristic Methods for Imposing Structure on Ill-Structured problems : Pople***

In AI in Medicine, Szolovits (*ed*), *AAAS Selected Symposium 51*, Westview Press, 1982

This addresses the nature of the clinical reasoning process and then offers a description, critique and a status report on INTERNIST(CADUCEUS).

- **AI Journal, Special issue on applications in the Sciences and medicine**
Volume 11, No. 1-2, Aug 1978

There are many interesting papers in this collection. Skim through this to get **an idea** of the kind of work going on and the main research issues. The following papers are recommended.

1. The plan recognition problem : an intersection of psychology and **AI**. By Schmidt, Sridharan and **Goodson**

This describes the BELIEVER system which encompasses **a** psychological theory **of** how humans understand actions of experts.

2. A model based method for computer aided medical decision making : **Weiss**, Kulikowski, Amarel and **Safir**

This is the CASNET paper.

3. Categorical and probabilistic reasoning in medical diagnosis : Peter Szolovits, **Pauker**

PIP, INTERNIST, CASNET and MYCIN are compared here.

7 Learning

Basic Reading

- ***The Handbook of Artificial Intelligence, Volume 3, William Kaujmann Inc., 1982, Chapter 14***

This is a comprehensive introduction to work on learning. It is a pre-requisite **to** understanding any of the subsequent material. This survey covers pre-1982 research only. For more recent work read the Machine Learning book referenced below.

Required papers

from the Webber and Nilsson collection of AI readings

- ***Generalization as Search : Mitchell, 1981***

Casts the generalization problem as a search problem. It provides **a framework for** comparing the various generalization strategies in learning literature.

- ***Interactive Transfer of Expertise : Acquisition of New Inference Rules : Randy Davis, 1979***

TEIRESIAS is described here. The most important contribution **is the acquisition of** knowledge in the context of a bug and the use of rule models obtained by induction on the existing set of rules. These are well explained in Section 7. Section 9 highlights the limitations of this approach and indicates open research questions.

Recommended reading

- ***The Computers and Thought Award Lecture : IJCAI 81 : Mitchell in the Proceedings of IJCAI 81***

Mitchell presents the problem of bias in generalization and the **need** for justified generalizations, with examples from LEX. Open problems in learning **are indicated**.

Highly recommended.

- ***Models of Learning Systems : Buchanan, Mitchell, Smith, Johnson***

STAN-CS-79-692, also in Encyclopedia of Computer Science and Technology, Dekker, Vol11,1978

This model of learning systems has proved extremely useful for understanding as well as designing learning programs. One of the components in this model (the Critic) was extremely well analyzed by Diet terich and Buchanan(see reference below).

- ***An overview of Machine learning : Carbonell, Michalaki and Mitchell in Machine learning : an AI approach, 1983, Tioga Publishing Co.***

A short sketch of current work in machine learning. Also includes a historical survey and a guide to the work presented in the later chapters in the book. Highly recommended.

- ***Why should machines learn? : Simon in Machine learning : an AI approach, 1983, Tioga Publishing Co.***

A short article giving Simon's views on machine learning. Every serious **machine** learning researcher should attempt to answer the questions that Simon raises. He **plays** devil's advocate here and concludes that with the exception of cognitive modeling, some rethinking of long term objectives in machine learning are in order.

- ***Learning by Experimentation : Acquiring and Refining Problem Solving Heuristics : Mitchell, Utgoff, Baneji in Machine Learning : an AI approach, 1983, Tioga Publishing Co.***

The LEX system is described. The most interesting section is 6.4 - where new term generation is discussed.

- ***The role of the critic in learning systems : Dietterich and Buchanan, 1981 STAN-U-81-891***

Also in Adaptive Control of Ill-defined Systems: Selfridge, Rissland and Arbib (eds)

This is a nice analysis of the task performed by the critic in a learning system. The style of analysis is as important as the contents here.

- ***Model directed learning of production rules : Buchanan and Mitchell***
in *Pattern Directed Inference Systems, ed. Waterman and Hayes-Roth, 1978*

The Meta-Dendral paper.

- ***The role of heuristics in learning by discovery : Lenat***
in *Machine learning : an AI approach, 1983, Tioga Publishing Co.*

Three case studies are presented here : AM, EURISKO and a speculation that nature **adopts a heuristic learning by discovery** approach to evolution. .

- ***Toward chunking as a general learning mechanism : Laird, Rosenbloom, Newell***
in *AAAI-84*

Chunking is presented as a general learning mechanism within a general problem solving architecture, SOAR. It is shown to exhibit both the practice effect as well as **strategy acquisition.**

Learning Apprentices[Mitchell84] form the major thrust of current work on machine learning. Analogy is a hot topic too: work by [Winston84], [Kling71], [Anderson83], [Gentner83], [Carbonell83] and [Greiner85] are worth reading. Genetic algorithms[Holland75], and work on incremental learning and experimentation[Dietterich84] are also being explored. The most recent work in machine learning is to be found in the proceedings of the Machine Learning Workshops (1983 and 1985). A new Machine learning journal will be published starting 1986 and will contain current research in the field.

8 Natural Language Understanding

This collection of readings covers both natural language understanding and speech recognition. Thanks go to John Lamping for helping me set up the syllabus for the **Natural Language understanding section**.

Basic Reading

- ***The Handbook of Artificial Intelligence, Volume 1, William Kaujmann Inc., 1982, Chapter 4***

This chapter should be read fairly carefully. Those interested in **details of grammars** and parsing should read Winograd's book **on the syntax of natural language** (see below). This chapter does not cover semantics and should **be augmented with Winograd's paper "What does it mean to understand language?"**. **To get a picture of what a present day Natural Language front-end looks like, read the Martin paper below.**

- ***The Handbook of Artificial Intelligence, Volume 1, William Kaujmann Inc., 1982, Chapter 5***

This is a fairly detailed account of the major speech understanding **projects of the 70's**. Compiling a comparison of these systems is instructive and is **suggested as an exercise**.

Required papers

- ***The Hearsay II Speech Understanding system : Erman et al., 1980 in the Webber-Nilsson collection***

This describes the HEARSAY architecture – a general framework **for coordinating** independent processes to achieve cooperative problem solving behavior in the **face** of uncertainty. The details of the different levels are unimportant, so skim **through the extended example** appropriately. The comparison with other **systems is interesting**. The section on performance is extremely important. Read the conclusions **carefully**.

- ***What does it mean to understand language? : Winograd***

in Cognitive Science, Vol 4, 1980, pp 209-241

Winograd explains the difficulties in understanding natural language. It is historically organized and represents Winograd's shifts in his thinking about natural language.

- TEAM : Paul Martin et. **al.**

in the proceedings of IJCAI 83

This should be read thoroughly for an idea of **a** modern natural language front end for data bases.

Recommended Reading

- ***A Semantic Process for Syntactic Disambiguation : Hirst***

in the Proceedings of AAAI 84

This should be scanned for understanding how semantic processing can work and how it can be combined with syntactic processing.

- ***Computational models of discourse : Brady and Berwick***

MIT Press

The first part of the introduction to this book (pages 27-37) should be read to **get a** feel for research issues in discourse.

- ***Language as a cognitive process : Vol I : Syntaz : Winograd***

Addison- Wesley, 1989

Read Chapter 1 and Chapter 7 and skim through the rest.

- ***Telling your computer to recognize speech not wreck a nice beach : Baker***

IBM Research report RC 6935, No. 29665

This is probably the 'cutest' title for an AI paper. The contents should be skimmed over.

- ***Utterance and Objective : Grosz***

in AI magazine : Vol 1 , No.1 , Spring 1980

The central issues of natural language from a communication perspective are described very clearly here. An updated version of this is to be found in the proceedings of IJCAI-85.

- ***Elements of a Plan-Based Theory of Speech Acts : Cohen and Perrault, 1979***

In the Webber and Nilsson collection

Language use is modeled by viewing speech acts as operators in a planning system thus allowing both physical and speech acts to be integrated into plans.

- ***Computers and Cognition : Winograd and Flores, Ablex, 1986***

An interesting perspective on Artificial Intelligence in general and language understanding in particular. The critique of the expert systems approach (Chapter **10**) is food for thought.

9 Vision and Robotics

Basic Reading

- ***The Handbook of Artificial Intelligence, 1982, William Kaujmann Inc., Volume 3, Chapter 13***

The overview should be read carefully. The blocks world work in **Section B** can be skimmed. The main ideas in these systems are indicated **in the handout on vision systems** in the course notes for **CS229b**. Edge detecting and line finding as **well** as analysis of texture are important research issues. The Brady **paper gives more** details on this. The various shape-from methods in **Section D** **are important. The** presentation is better in Brady. Read the section on relaxation algorithms **carefully**. Vision systems should be understood well, particularly ACRONYM.

- ***Artificial Intelligence (2nd ed.), Patrick Winston, 1984, Addison- Wesley, Chapter 10***

This is a nice account of some of the more recent work in vision **and is a pre-requisite** to understanding the Brady paper.

- ***Computational Approaches to Image Understanding : Brady***

in ***Computing Surveys, Vol. 14, No. 1, March 1982***

A survey of the recent developments in Image Understanding. The **first part of the** paper identifies the field of image understanding by delineating it from pattern **recognition**, image processing and computer graphics. This is followed by a description **of** the common themes in IU research that have crystallized over the **past decade. Then** there is a very nice review of work in geometrically simple **microworlds (Roberts, Huffman and Clowes, Mackworth, Kanade, Turner, Barrow and Tenenbaum, Waltz)**. Operations on the image : edge detection, shape from shading, **segmentation and** texture are described. Shape from stereo, contour and motion are surveyed next. **The** paper ends with a survey of work on representing **3D** objects.

Recommended Reading

- **Task Planning : Tomas Lozano- Perez**

In Robot Motion : Planning and Control, eds Brady et al., MIT Press, 1982

This is a primer on task planning. Task planning is divided into three phases : modelling, task specification and manipulator program synthesis. Note similarities and differences in the approaches to specification and synthesis with respect to automatic programming and planning.

- **Survey of Model Based Image Analysis Systems : Binford**

SAIL Tech. report

This paper surveys and critiques the state of the art in model based image analysis systems. It also describes principles of design of general vision systems.

- **Perceptual Organization as a Basis for Visual Recognition : Lowe and Binford**
in ***the Proceedings of AAAI 83.***

Evidence is presented that bottom-up grouping of image features is usually prerequisite to the recognition and interpretation of images. Several principles are hypothesized for determining which image relations are to be formed. Using this, a curve segment ation algorithm is presented.

- **Automated Visual Inspection : Chin et al.**

in the IEEE Transactions of Pattern Analysis and Machine Intelligence, .

Skim through this paper to get a sense of the kinds of applications in visual inspection in industry.

- **AI Journal, Special Issue on Computer Vision : Aug 1981**

The articles worth reading here are

- The Preface by Michael Brady. This was probably what developed into the paper described above.

- Inferring Surfaces from Images : **Binford**
- Symbolic Reasoning among 3-D models and 2-D images : Brooks

Read the introductions (or skim through the contents of) the remaining articles which should be taken as representative of current vision research.

10 Advanced Topics

This is a pot-pourri of topics which are necessary for a well-rounded understanding of AI.

- Advanced reasoning/planning
 - Circumscription : a form of Nonmonotonic Reasoning, McCarthy, 1980
In Readings in AI, Webber and Nilsson (eds), 1982
 - Reasoning about Knowledge and Action : Moore, 1977
In Readings in AI, Webber and Nilsson (eds), 1982
 - A Truth Maintenance System : Doyle, **1979**
In Readings in AI, Webber and Nilsson (eds), 1982
 - Assumption Based Truth Maintenance : deKleer, **1984**
Xerox PARC Technical Note
 - Computation and Deduction : Hayes
Proceedings of the Czech. Academy of Sciences, 1978
 - Design of a Programmer's Apprentice : Rich and Schrobe, **1979**
In AI : An MIT Perspective, Winston and Brown (eds), MIT Press, 1979
 - Qualitative and quantitative reasoning in classical mechanics : deKleer, 1979
In AI : An MIT Perspective, Winston and Brown (eds), MIT Press, 1979
 - On Inheritance Hierarchies with Exceptions : Etherington **and Reiter, 1984**
In the Proceedings of the AAAI-84
 - Nonmonotonic reasoning : Genesereth and Nilsson, **1985**
In their forthcoming book on AI
 - Learning by Experimentation : Acquiring and Refining Problem Solving Heuristics : Mitchell, Utgoff, Banerji, 1983
in Machine Learning : an AI approach, 1983, Tioga Publishing Co.

- Common knowledge : Halpern and Moses, 1984
IBM Tech. Report, 1984
- Advanced **KR/Software** architectures
 - The Logic of **Frames** : Hayes, 1979
In Readings in AI, Weber and Nilsson (eds), 1982
 - Meta-level architecture : Genesereth and Smith, 1983
In the proceedings of AAAI-83
 - Towards Chunkiness as a General Learning Mechanism: Laird, Rosenbloom and Newell, 1984
In the Proceedings of AAAI-84
 - A Blackboard Model of Control : Barbara Hayes-Roth, 1985
AI Journal, 1985
 - OPS, A Domain Independent Production System Language, 1977
In the Proceedings of IJCAI-77
- Advanced architectures for AI

Thanks to Vineet Singh for extending and annotating this list. Notation used below:
I : introduction to issues, R : resource allocation, L : language, H : hardware and architecture.

 - What should AI want from supercomputers : Doyle. (I)
AI Magazine, Vol 4, No. 4, Winter 1983
 - The Connection Machine : Dan Hillis (H)
MIT AI Lab memo, AIM 646
 - DADO: a tree structured architecture for production systems : Stolfo and Shaw (H)
In the Proceedings of IJCAI-83

- A Variable Supply Model for Distributing Deductions : Singh and Genesereth (R)

In the Proceedings of IJCAI-85, also HPP-84-14

- &LAMBDA : Gabriel and McCarthy. (L)

STAN-CS-84-1007

- A subset of Concurrent Prolog and its Interpreter : Shapiro (L)

TR-003, ICOT, Japan

- Hardware and Software Architectures for AI : Deering (I)

In the Proceedings of AAAI-84

- The Architecture of the FAIM-1 Symbolic Multiprocessing System : Davis and Robison (H,L,R)

In the Proceedings of IJCAI-85

- NETL : A System for Representing and using Real-World Knowledge: Fahlman, 1979

MIT PhD thesis, MIT Press, 1979

• **Philosophical/Epistemological issues**

- Some Philosophical Problems from the Standpoint of AI : McCarthy, 1969

In Readings in AI, Webber and Nilsson (eds), 1982

- Epistemological problems of AI : McCarthy, 1977

In Readings in AI, Webber and Nilsson (eds), 1982

- Programs with Common Sense (The Advice Taker): McCarthy

In Semantic Information Processing,, Minsky (ed), 1968

- The Second Naive Physics Manifesto : Hayes, 1985

In Formal Theories of the Commonsense World, Hobbs and Moore (eds), Ablex, 1985

- Ascribing Mental Qualities to Machines : McCarthy, 1979
STAN-CS-79-725
- A perspective on planning : Stan Rosenschein
in the proceedings of AAAI-84
- AI meets Natural Stupidity : Drew McDermott, 1976
SIGPLAN Newsletter, Number 57, pages 4-9
also in Mind Design edited by J. Haugeland, MIT Press, 1981
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- What Computers Can't Do: A Critique of Artificial Reason : **Dreyfus**, 1972
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11 Acknowledgements

We would like to thank Prof. Nils **Nilsson** who patiently read through innumerable drafts of this reading list and made constructive suggestions. Thanks also to Chris Fraley, **Vineet** Singh and Stuart Russell for their comments on a very early version of this document. Members of **CS229b** in this and in the previous year (Winter 84, **TA'ed** by Ben Grosf), provided considerable input.



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